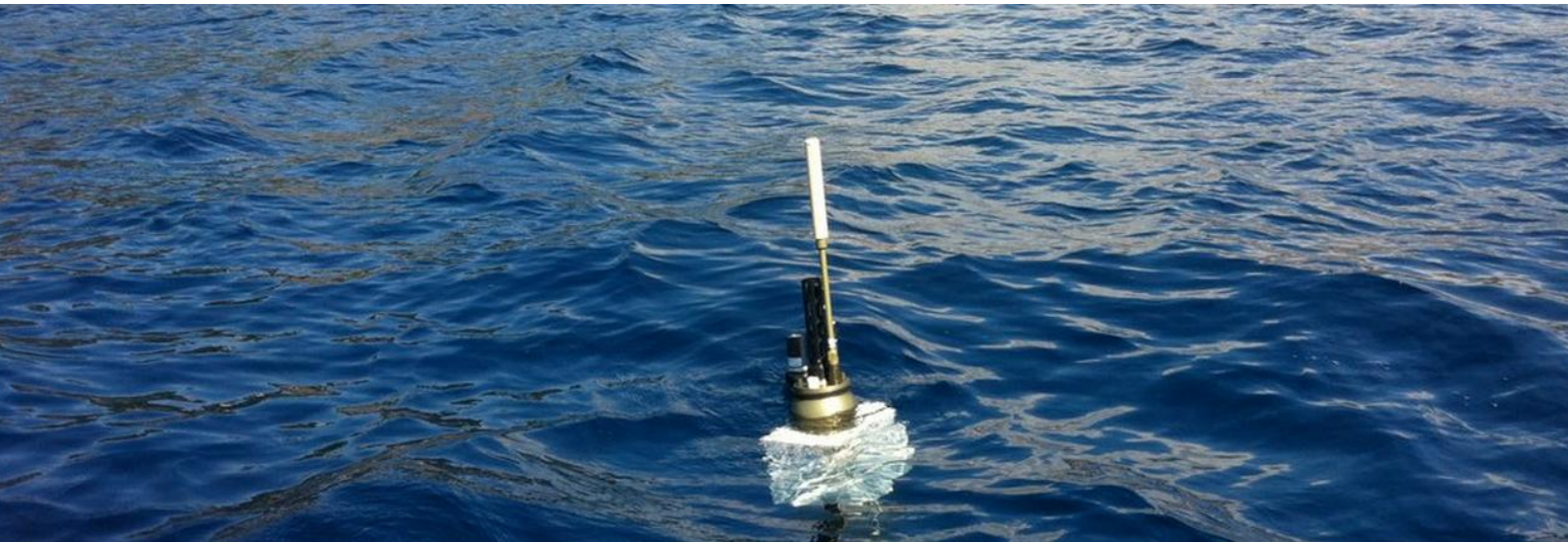# APMT Profiler - File management

AUTOMATED **M**ULTI-**T**ASK **P**ROFILER

33-16-046_APMT_File_Management
Revision 1.11 (2021-06-03)

Table of contents

1. Revision history

Revision	Release date	Notes	Author
1.0	2017-09-04	Original	C. SCHAEFFER
1.1	2018-02-15	Upgrade of technical information: - Adding internal temperature information in [SYSTEM] - Adding pressure activation information in [ACTIVATION] - Adding nke ID information in [USER] - Changing grounding information during navigation phases in [PROFILE] and [ALARM] - Changing feedback information in [ALARM]	C. SCHAEFFER
1.2	2018-11-19	Upgrade of technical information: - Adding pressure reference in "VBatt peak min" tag - Adding USEA identification in [USER] - Adding sensor identification [SENSOR_xxx] - Adding surface sample count in [DATA] - Adding sensor tag in [POWER] - Adding alarms flag in [ALARM] Upgrade of sensor data files: - Adding navigation phase [SURFACE] - Adding decimated raw treatment tag (DW) - Adding a 100 dbar offset in SBE41 pressure - Adding DO, OCR, ECO, C-ROVER, SBEPH, SUNA data format	C. SCHAEFFER
1.3	2019-12-12	Upgrade of technical information: - Adding metadata files - Removing redundant information [USER] - Removing redundant information [SENSOR_xxx] - Changing "kB" into "KB" Upgrade of sensor data files - Adding UVP6 data formats Update SBE41 *.hex standard format: - Adding time stamping for each record Upgrade of technical information: - Adding ice capabilities alarms	C. SCHAEFFER
1.4	2020-01-20	Upgrade of sensor data files - Adding EXTTRIG data format	C. SCHAEFFER
1.5	2020-02-11	Upgrade of sensor data files - Adding ECOv2 data format - Adding technical and metadata information related to ECOv2	C. SCHAEFFER
1.6	2020-03-12	Upgrade of technical information - Adding ice braking and perigee in [PROFILE] - Adding alarm flag in [ALARM]	C. SCHAEFFER
1.7	2020-08-26	Upgrade of technical and sensor data files - Adding RAMSES data format	C. SCHAEFFER
1.8	2020-09-30	Upgrade of metadata file: - Changing profiler model format - Adding APMT's SD card information	C. SCHAEFFER

		- Adding BATTERY information - Adding SBE41 firmware information	
1.9	2020-12-16	Upgrade of technical and sensor data files - Adding OPUS data format Upgrade of metadata file: - Adding PROFILER.ID information - Adding TELECOM.Login information - Adding ECO.Type information - Adding EXTENSION_BOARD information - Adding HULL information - Adding SBE41 calibration coefficients - Adding CONTROL_BOARD and MEASURE_BOARD SN information	C. SCHAEFFER
1.10	2021-04-07	Upgrade of technical and sensor data files - Adding MPE data format - Adding [POWER].Measure information	C. SCHAEFFER
1.11	2021-06-03	Upgrade of technical and sensor data files - Adding SBEPH technical information - Adding UVP6 LPMv2, TXOv2 and BLKv2 data format - Adding UVP6-TXO technical information - Deleting UVP6-TX1 and UVP6-TX2	C. SCHAEFFER

2. File system

Float management is based on a specific file system developed by nke. This file system allows information and data to be stored when the float is turned off, together with the mission configuration.

These files can be accessed by an FTP client via the Bluetooth connection.

2.1 Memory organisation

The memory space is divided into different areas intended for different uses. In particular, the following spaces can be found:

- Reserved: restricted system use to store file manipulation and management information
- Working: used for temporary storage (awaiting transmission).
- Storage (optional): used to expand the temporary storage capacity of the workspace

2.2 File types

The system uses various file types, as needed:

- Configuration file for mission and sensor settings
- Sensor data files (raw, processed and transmitted data)
- Technical data files
- Metadata files (for sensor specific identification)
- Execution trace files (mission progress monitoring)
- Specific files (restricted system use)

2.3 Main memory – Working memory

The working memory (fast access) is itself divided into two physical spaces:

- Area for repeated access files: used for files with recurring access (configuration file...)
- Area for temporary files: used mainly for the generation of sensor information and data during the various navigation phases (a process that automatically deletes the oldest files in favour of new ones allows a minimum free memory space to be maintained)

2.4 Extended memory – Storage memory (optional)

When the application requires it, the use of an additional memory (slow access) allows the storage capacity of the system to be increased.

In this case, the files (awaiting transmission) deleted from the working memory are moved to the extended memory. They will then be repatriated to the working memory (for transmission) when the main memory space is sufficient.

3. Configuration files

The mission configuration is saved as a text file organised by sections and tags.

3.1   Local configuration via Bluetooth

During the mission configuration phase performed locally via Bluetooth, this file can be written and/or modified by the user. It can be manually uploaded in full using an FTP client or partially modified with a TELNET command interpreter.

3.2   Remote configuration via remote commands

When the mission is in progress, the file can be modified by sending remote commands via the satellite communication system (RUDICS...).

3.3   Transmission of the configuration file

The system transmits the current configuration file at various stages of the mission:

-   At the start of the mission (initial configuration)
-   Upon a change of configuration following the application of a remote command or pre-programmed change (script)

The various files generated are named using the format "xxxx_ccc_mm_apmt.ini", with:

-   "xxxx": float's hexadecimal serial number (4 characters)
-   "ccc": cycle number (3 characters)
-   "mm": pattern number (2 characters)

4. Technical files

The various pieces of technical information associated with a profile are saved in a text file organised by sections.

4.1   Transmission of technical information

The system transmits technical files at various stages of the mission:

- During system verification prior to the mission (self-test)
- During the mission at the end of each pattern
- At end of life

4.1.1. Self-test files

The files generated are named using the format "xxxx_ccc_autotest_nnnnn.txt", with:

- "xxxx": float's hexadecimal serial number (4 characters)
- "ccc": cycle number (3 characters)
- "nnnnn": identification of self-test file number associated with the cycle (5 characters)

4.1.2. Mission files

The files generated are named using the format "xxxx_ccc_mm_technical.txt":

- "xxxx": float's hexadecimal serial number (4 characters)
- "ccc": cycle number (3 characters)
- "mm": pattern number (2 characters)

Note: A pattern numbered "00" corresponds to a pre-mission file.

4.1.3. End-of-life files

The various files generated are named using the format "xxxx_ccc_mm_default_nnnnn.txt", with:

- "xxxx": float's hexadecimal serial number (4 characters)
- "ccc": cycle number (3 characters)
- "mm": pattern number (2 characters)
- "nnnnn": identification of end-of-life file number associated with the cycle/pattern pair (5 characters)

4.2   Technical information available

The data is organised in sections. The various sections and fields that compose them are optional and may not be present in the files.

[SYSTEM]

Information	Format
External pressure offset	Pe offset=xx.xx dbar
Internal pressure	Pi=xxx.x mbar
No-load battery voltage	Vbatt=xx.x V
Battery voltage under load (min.)	Vbatt peak min=xx.x V (xx dbar)
External temperature (air)	Te air=xx.x degC
External pressure (air)	Pe air=xx.x dbar
Internal temperature	Ti=xx.x degC

[GPS]

Information	Format
Time stamping, position (*) and clock drift (**)	UTC=yy-mm-dd hh:mm:ss Lat=ddmm.mmmmh Long=dddmm.mmmmh Clock drift=xx.xxx s

(*) Geographic coordinates are coded in DM format (degrees, minutes and decimal minutes – NMEA standard). For example: "Lat=4747.846N Long=00317.160W" represents 47°47.846'N 3°17.160'W coordinates.

(**) Drift = Float time - GPS time. The offset is reset to 0 after every GPS retiming.

[USER]

Information	Format
nke ID	WC=xxxxxxxxxx

[ACTIVATION]

Information	Format
Pressure activation start	UTC=yy-mm-dd hh:mm:ss Detection start
Pressure activation stop	UTC=yy-mm-dd hh:mm:ss Detection stop

[PROFILE]

Information	Format
Emergence reduction: - Start date/time - Oil volume transferred - Nb. solenoid valve actions	UTC=yy-mm-dd hh:mm:ss Flotation=xxx.x cm3 (xx)
First stabilization - Date/time - Depth	UTC=yy-mm-dd hh:mm:ss First stabilization=xxx dbar
Park descent: - Start date/time - Oil volume transferred - Nb. solenoid valve actions	UTC=yy-mm-dd hh:mm:ss Descent=xxx.x cm3 (xx) UTC=yy-mm-dd hh:mm:ss Descent_y=xxx.x cm3 (xx) (****)
Grounding park descent:	UTC=yy-mm-dd hh:mm:ss Grounding Descent=xxx dbar

- Start date/time - Grounding pressure	UTC=yy-mm-dd hh:mm:ss Grounding Descent_y=xxx dbar (****)
Grounding park descent: - End date/time - Oil volume transferred	UTC=yy-mm-dd hh:mm:ss Grounding Descent escape=xxx.x cm3
Park drift: - Start date/time - Min. depth - Max. depth - Nb. solenoid valve actions - Nb. pump actions - Nb. set point inputs - Nb. set point outputs	UTC=yy-mm-dd hh:mm:ss Park=xxx/xxx dbar (xx/xx) stability=x/x UTC=yy-mm-dd hh:mm:ss Park_y=xxx/xxx dbar (xx/xx) stability=x/x (****)
Stabilized park drift: - Stabilization date/time - Stabilization depth	UTC=yy-mm-dd hh:mm:ss Park stabilization=xxx dbar UTC=yy-mm-dd hh:mm:ss Park_y stabilization=xxx dbar (****)
Grounding park drift: - Start date/time - Grounding number (1-5) - Grounding pressure	UTC=yy-mm-dd hh:mm:ss Grounding Park x=xxx dbar
Grounding park drift: - End date/time - Grounding number (1-5) - Oil volume transferred	UTC=yy-mm-dd hh:mm:ss Grounding Park x escape=xxx.x cm3
Measurement descent: - Start date/time - Oil volume transferred - Nb. solenoid valve actions	UTC=yy-mm-dd hh:mm:ss Deep profile=xxx.x cm3 (xx)
Grounding measurement descent: - Start date/time - Grounding pressure	UTC=yy-mm-dd hh:mm:ss Grounding Deep profile=xxx dbar
Grounding measurement descent: - End date/time - Oil volume transferred	UTC=yy-mm-dd hh:mm:ss Grounding Deep profile escape=xxx.x cm3
Measurement drift: - Start date/time - Min. depth - Max. depth - Nb. solenoid valve actions - Nb. pump actions - Nb. set point inputs - Nb. set point outputs	UTC=yy-mm-dd hh:mm:ss Short Park=xxx/xxx dbar (xx/xx) stability=x/x
Grounding short park drift: - Start date/time - Grounding number (1-5) - Grounding pressure	UTC=yy-mm-dd hh:mm:ss Grounding Short park x=xxx dbar
Grounding short park drift: - End date/time - Grounding number (1-5) - Oil volume transferred	UTC=yy-mm-dd hh:mm:ss Grounding Short park x escape=xxx.x cm3
Ascent (standard):	UTC=yy-mm-dd hh:mm:ss Ascent=xxx.x cm3 (xx/xx) from xxx

- Start date/time - Oil volume transferred - Nb. pump actions (total) - Nb. actions for take-off - Maximum depth	dbar
Ascent (slow): - Start date/time - Oil volume transferred - Nb. pump actions	UTC=yy-mm-dd hh:mm:ss Ascent (slowly)=xxx.x cm3 (xx)
Ascent (resume): - Start date/time - Oil volume transferred - Nb. pump actions	UTC=yy-mm-dd hh:mm:ss Ascent (resume)=xxx.x cm3 (xx)
Ascent (end) - End date/time	UTC=yy-mm-dd hh:mm:ss Ascent end
Ice abort: - Abort date/time - Oil volume transferred - Abort pressure	UTC=yy-mm-dd hh:mm:ss Abort=xxx.x cm3 at xxx dbar
Ice perigee: - Perigee date/time - Perigee pressure	UTC=yy-mm-dd hh:mm:ss Perigee=xxx dbar
Surface - Start date/time	UTC=yy-mm-dd hh:mm:ss Surface
Hanging: - Start date/time - Hanging pressure	UTC=yy-mm-dd hh:mm:ss Hanging=xxx dbar
Hanging: - End date/time	UTC=yy-mm-dd hh:mm:ss Hanging escape
Park drift (ice): - Start date/time - Min. depth - Max. depth - Nb. solenoid valve actions - Nb. pump actions - Nb. set point inputs - Nb. set point outputs	UTC=yy-mm-dd hh:mm:ss Ice Park=xxx/xxx dbar (xx/xx) stability=x/x
Stabilized park drift (ice): - Stabilization date/time - Stabilization depth	UTC=yy-mm-dd hh:mm:ss Ice Park stabilization=xxx dbar
Pressure switch activation	UTC=yy-mm-dd hh:mm:ss Pressure switch activation
Emergency ascent - Start date/time	UTC=yy-mm-dd hh:mm:ss Emergency ascent

Typical rate of descent can be calculated with: "Park drift" UTC - "Emergence reduction" UTC
Typical rate of ascent can be calculated with: "Ascent (end)" UTC – "Ascent (standard)" UTC

[DATA]

Information	Format
Data transmission (*): - Total data size - Nb. files - Average baud rate - Nb. sessions	Upload=xx.x KB of x file(s) at x.x KB/min in x session(s)
Remote command reception: - Nb. accepted - Nb. refused - Nb. unknown	Download=command file (x accepted, x refused, x unknown)
Payload configuration download	Download=payload file
Script download	Download=script file
Number of files associated with the pattern (**)	Pattern=x files
Number of points per sensor: - Sensor name [SBE41, DO, OCR, ECO, ECOv2, CROVER, SBEPH, SUNA, UVP6-LPM, UVP6-TXO, UVP6-BLK, EXT-TRIG, RAMSES, OPUS-LGT, OPUS-BLK] - Nb. park descent - Nb. park drift - Nb. measurement descent - Nb. measurement drift - Nb. ascent - Nb. surface - Nb. subsurface (***)	xxxxx=x/x/x/x/x/x points or xxxxx=x/x/x/x/x/x/x points (***)

(*) Information from the previous transmission session.
(**) The following files are not taken into account: technical for self-test or pre-mission, configuration nor command/script acknowledgement. The number of files is expressed prior to the files being broken down for transmission.
(***) SBE41 only
(****) With multi-parking navigation scheme

[POWER]

Information	Format
Pattern duration	Pattern=x min
Processing/standby ratio	Treatment=xx % Measure=xx %
Cumulated hydraulic activations: - Solenoid valve - Pump	EV/Pump=xxx/xxx cs
Cumulated modem activations (*)	Transmission=xxx min
Cumulated GPS activations	GPS=xxx s
Cumulated sensor activations: - Sensor name [SBE41, DO,	xxxx=xxx min

OCR, ECO, ECOv2, CROVER, SBEPH, SUNA, UVP6, EXT-TRIG, RAMSES, OPUS,MPE] - Duration	

(*) Information from the previous transmission session.

[ALARM]

Information	Format
Deployment	
Start up	Power-on
Invalid configuration	Bad configuration
Excessively heavy float	Flotation (heavy)
Excessively light float	Flotation (light)
Self-test failure: - Source(s) xxx among "FRAM, FLASH, RTC, Vbatt, Pi, Pe, SBE41-Cutoff, SBE41-Offset, GPS, Payload, USEA, Sensor(xxx), Transmitter"	Autotest fail=xxx, …
State	
No-load battery voltage low	Vbatt low
Battery voltage under load low	Vbatt peak low
Low external pressure	Pe low (xxx dbar)
High external pressure	Pe high (xxx dbar)
External pressure fault	Pe default
External breaking pressure	Pe broken
Gear skip	Pe SR high
High internal pressure	Pi high
Presence of water	Water inside
Navigation	
Grounding during park descent	Grounding Descent (xxx dbar) Grounding Descent_y (xxx dbar) (****)
Grounding during park drift	Grounding Park x (xxx dbar)
Grounding during measurement descent	Grounding Deep profile (xxx dbar)
Grounding during short park drift	Grounding Short park x (xxx dbar)
Hanging during ascent	Hanging (xxx dbar)
Braking during descent	Braking
Operating errors	
System fault	System
Payload board fault	Payload
GPS fault	GPS
Hydraulic fault	Hydraulic
ADC fault	ADC
File fault	File (skip)

RTC fault	RTC
Pressure switch fault	Pressure switch
Ice capabilities	
Ice avoidance (ISA detection)	Ice (ISA)
Ice avoidance (collision detection)	Ice (collision)
Ice avoidance (aborting profile)	Ice (abort)
Ice avoidance (cover detection)	Ice (cover)
Ice avoidance (no surface period)	Ice (period)
Mode switch	
End of life: - Source xxx among "Pi high, Pe broken, Pe high, Vbatt low, Vbatt peak low, Water inside, Flotation (heavy), Flotation (light)"	End of life (xxx)
Rescue procedure	Rescue
Feedback: - Type xxx among "Early profile, Early surface, Abort profile, Abort cycle 0, Abort cycle 1, Go to deep, Standard speed, Lower speed" - Nb. accepted - Nb. refused	Feedback=xxx (x accepted, x refused) Feedback=xxx (x accepted, x refused) …
Sensors	
Bad value in data frame: - Sensor name [SBE41, DO, OCR, ECO, ECOv2, CROVER, SBEPH, SUNA, UVP6, RAMSES, OPUS, MPE] - Error count	xxx value (xxx)
No reply/framing error: - Sensor name [SBE41, DO, OCR, ECO, ECOv2, CROVER, SBEPH, SUNA, UVP6, RAMSES, OPUS, MPE] - Error count	xxx default (xxx)
Repetitive default: - Sensor name [SBE41, DO, OCR, ECO, ECOv2, CROVER, SBEPH, SUNA, UVP6, RAMSES, OPUS, MPE]	xxx broken
Data size: - Sensor name [SBE41, DO, OCR, ECO, ECOv2, CROVER, SBEPH, SUNA,	xxx size (xxx.x KB)

Information	Format
UVP6-LPM, UVP6-TXO, UVP6-BLK, EXT-TRIG, RAMSES, OPUS-LGT, OPUS-BLK, MPE] - Data size	

[SENSOR_SUNA]

Information	Format
Counters: - Sample counter - Power cycle counter - Error counter	Counters=892340/852111/16
Power supply: - Voltage - Intensity	Power supply=9.53 V/0.663 A

[SENSOR_SBEPH]

Information	Format
First ascent frame: - Vref - Vk - Ik - Ib	First=x.xxxxxx/x.xxxxxx/x.xxxxxx/x.xxxxxx at xxxx.x dbar
Last ascent frame: - Vref - Vk - Ik - Ib	Last=x.xxxxxx/x.xxxxxx/x.xxxxxx/x.xxxxxx at x.x dbar

[SENSOR_UVP6]

Information	Format
SD memory free space	Available space=xxx.x GB

Example:

[USER]
WC=85E386B7C7
[SYSTEM]
Pe offset=0.00 dbar
Pe air=0.00 dbar
Pi=750.3 mbar
Vbatt=10.7 V
Vbatt peak min=10.0 V (0 dbar)
[GPS]
UTC=18-11-20 12:17:24 Lat=4310.35000S Long=00555.02500W Clock drift=+0.000 s
[PROFILE]
UTC=18-11-20 10:12:22 Flotation=10.7 cm3 (1)
UTC=18-11-20 10:34:03 First stabilization=9 dbar
UTC=18-11-20 10:23:45 Descent=12.2 cm3 (4)
UTC=18-11-20 11:33:06 Park=68/68 dbar (0/0) stability=0/0
UTC=18-11-20 11:33:08 Deep profile=0.0 cm3 (0)
UTC=18-11-20 11:34:06 Short Park=68/68 dbar (0/0) stability=0/0
UTC=18-11-20 11:34:07 Ascent=24.6 cm3 (12/4) from 69 dbar
UTC=18-11-20 12:00:25 Ascent end
UTC=18-11-20 12:10:25 Surface
[DATA]
Upload=4.8 KB of 3 file(s) at 10.2 KB/min in 1 session(s)
Pattern=6 files
SBE41=47/0/0/0/30/6/1 points
OCR=95/0/0/0/33/0 points
ECO=86/0/0/0/30/0 points
SBEPH=58/0/0/0/32/0 points
SUNA=7/0/0/0/4/0 points
[POWER]
Pattern=126 min
Treatment=1 %
EV/Pump=337/382 cs
SBE41=115 min
Transmission=2 min
GPS=260 s
OCR=6 min
ECO=6 min
SBEPH=6 min
SUNA=1 min
[SENSOR_SUNA]
Counters=892340/852111/16
Power supply=9.53 V/0.663 A

5. Metadata files

5.1.Transmission of metadata information

Metadata files are transmitted once at the beginning of the mission.

The files generated are named using the format "xxxx_ccc_mm_metadata.xml", with:

- "xxxx": float's hexadecimal serial number (4 characters)
- "ccc": cycle number (3 characters)
- "mm": pattern number (2 characters)

5.2.Metadata information available

Metadata information are organised in XML format.

[PROFILER]

Information	Format
Identification: - Serial number - Identifier - Model	<PROFILER SN="P5XXXX-XXXXXXX" ID="0xXXXX" Model="PROVOR_V"/>

[TELECOM]

Information	Format
Identification: - Type - SIM card ID - Account login	<TELECOM Type="IRIDIUM" CID=" xxxxxxxxxxxxxxx" Login="xxxxx"/>

[HARDWARE]

Information	Format
Control board identification: - Model - Serial number - Firmware version - SD card status	<CONTROL_BOARD Model="APMT" SN="CYYMMDD-XXXX" Firmware="x.xx.xxx" SDCard="Installed/Not installed"/>
Measure board identification: - Model - Serial number - Firmware version	<MEASURE_BOARD Model="USEA" SN="CYYMMDD-XXXX" Firmware="x.xx.xxx"/>
Extension board identification: - Model	<EXTENSION_BOARD Model="EXTEND"/>
Battery configuration: - Pack number "x" information - Type - Voltage	<PACK_x Type="Lithium" Voltage="10.8 V" Capacity="xxx Ah"/>

- capacity	
Hull configuration: - Model	<HULL Model="Type x"/>

[SENSOR_SBE41]

Information	Format
Identification: - Serial number - Model	<SENSOR SN="XXXXX" Model="SBE41-CP"/>
Sensor board identification: - Firmware version	<SBE41_BOARD Firmware="x.x.x"/>
Pressure sensor Identification: - Serial number	<SENSOR_PRESSURE SN="XXXXX"/>
Temperature correction: - Coefficients	<TEMPERATURE_COEFF ta0="xxxx" ta1="xxxx" ta2="xxxx" ta3="xxxx"/>
Conductivity correction: - Coefficients	<CONDUCTIVITY_COEFF g="xxxx" h="xxxx" i="xxxx" j="xxxx" ctcor="xxxx" cpcor="xxxx" wbotc="xxxx"/>
Pressure correction: - Coefficients	<PRESSURE_COEFF pa0="xxxx" pa1="xxxx" pa2="xxxx" ptca0="xxxx" ptca1="xxxx" ptca2="xxxx" ptcb0="xxxx" ptcb1="xxxx" ptcb2="xxxx" ptha0="xxxx" ptha1="xxxx" ptha2="xxxx" poffset="xxxx"/>

[SENSOR_DO]

Information	Format
Identification: - Serial number - Model	<SENSOR SN="XXXXX" Model="DOxxx"/>
Phase correction: - Coefficient "c0"	<PHASE_COEFF c0="xxxx"/>
SVU foil correction: - Coefficient "c0" - ... - Coefficient "c6"	<SVU_FOIL_COEFF c0="xxxx" c1="xxxx" ... c6="xxxx"/>

[SENSOR_OCR]

Information	Format
Identification: - Serial number - Model	<SENSOR SN="XXXXX" Model="OCRxxx"/>
Channel correction: - Index [4,7 or 14] - Coefficient "a0" - Coefficient "a1" - Coefficient "im"	<CHANNEL_xx a0="x.xxxx" a1="x.xxxx" im="x.xxxx"/>

[SENSOR_ECO]

Information	Format
Identification: - Serial number	<SENSOR SN="XXXXX" Model="ECOxxx" Type="xxxxxx"/>

Information	Format
- Model - Type	
Channel correction: - Index [1-3] - Scale factor "sf" - Dark count "dc"	<CHANNEL_xx sf="x.xxxx" dc="xxxxxxx"/>

[SENSOR_ECOv2]

Information	Format
Identification: - Serial number - Model	<SENSOR SN="XXXXX" Model="ECOxxx"/>
Channel correction: - Index [1-3] - Scale factor "sf" - Dark count "dc"	<CHANNEL_xx sf="x.xxxx" dc="xxxxxxx"/>

[SENSOR_CROVER]

Information	Format
Identification: - Serial number	<SENSOR SN="XXXXX"/>
Path length: - X value "pth" (cm)	<PATH_LENGTH pth="xx.xx"/>
Calibration: - CSCcal value "cln"	<CALIBRATION cln="xxxxx"/>

[SENSOR_SBEPH]

Information	Format
Identification: - Serial number	<SENSOR SN="XXXXX"/>

[SENSOR_SUNA]

Information	Format
Identification: - Serial number - Model - Output pixel begin - Output pixel end	<SENSOR SN="XXXXX" Model="SUNA-V2" Spectrum="Output pixels xx-xx"/>
Sensor board identification: - Firmware version	<SUNA_BOARD Firmware="x.x.xx"/>
Spectrometer: - Integration time "spintper"	<SPECTROMETER spintper="xxx"/>

[SENSOR_UVP6]

Information	Format
Identification: - Serial number - Model	<SENSOR SN="XXXXXXXXXXX" Model="UVP6-LP"/>
HW configuration	<HW_CONF frame="xxxxxxxxxx">

| ACQ configuration:
- Index [1-10] | <ACQ_CONF_xx frame="xxxxxxxxxx"> |
| TAXO configuration:
- Index [1-10] | <TAXO_CONF frame="xxxxxxxxxx"> |

[SENSOR_RAMSES]

Information	Format
Identification: - Serial number	<SENSOR SN="XXXXX"/>
Sensor board identification: - Firmware version	<RAMSES_BOARD Firmware="x.x.xx"/>
Spectrum: - Wavelengths number - Wavelengths	<SPECTRUM Length="xx" Wavelengths="xx.xxx,[...],xx.xxx"/>

[SENSOR_OPUS]

Information	Format
Identification: - Serial number	<SENSOR SN="XXXXX"/>
Sensor board identification: - Firmware version	<OPUS_BOARD Firmware="x.x.xx"/>
Spectrum: - Wavelengths number - Wavelengths	<SPECTRUM Length="xxx" Wavelengths="xx.xxx,[...],xx.xxx"/>
Lamp Identification: - Serial number	<SENSOR_LAMP SN="xxxxx"/>
Spectrometer: - Optical path size	<SPECTROMETER Path="xx mm"/>
Waterbase reference spectrum: - Wavelengths number - Intensities	<WATERBASE Length="xxx" Intensities="xx.x,[...],xx.x"/>

[SENSOR_MPE]

Information	Format
Identification: - Serial number - Type	<SENSOR SN="XXXXX" Type="xxxx"/>
Acquisition settings: - Averaging - Rate	<ACQUISITION Average="122" Rate="125"/>
Photodetector: - Responsivity in water - Responsivity in air - Units	<PHOTODETECTOR ResponsivityW="0.795" ResponsivityA="0.995" Units="uE/(cm2 s)"/>
Microradiometer: - Gain ration High-Medium - Gain ration Medium-Low - Offsets High/Medium/Low	<MICRORADIOMETER GainHM="217.7360077" GainML="198.2780151" OffsetH="8388592" OffsetM="8388840" OffsetL="8388840"/>

Example:

```xml
<FLOAT>
    <PROFILER SN="AABBCC-DDEEFFF" Model="PROVOR-V"/>
    <TELECOM Type="IRIDIUM" CID="8988169224001045237"/>
    <HARDWARE>
        <CONTROL_BOARD Model="APMT" Firmware="1.07.019"/>
        <MEASURE_BOARD Model="USEA" Firmware="1.00.019"/>
    </HARDWARE>
    <SENSORS>
        <SENSOR_UVP6>
            <SENSOR SN="000001HF" Model="UVP6-LP"/>
            <HW_CONF frame="000001HF,0,ACQ_NKE_00h,0,001,1,150,250,,999.000,393819,10000,2,192.16
            <ACQ_CONF_01 frame="ACQ_NKE_00H,0,1.000,1,1,0,0,1,1,10,0,500,1.0,10,10,0,1000,0,40,la
            <ACQ_CONF_02 frame="ACQ_NKE_00L,0,1.000,1,1,0,0,1,1,10,0,500,1.0,100,10,0,1000,0,40,1
            <ACQ_CONF_03 frame="ACQ_NKE_01H,0,1.000,1,1,0,0,1,1,10,0,500,1.0,10,10,0,1000,0,40,la
            <ACQ_CONF_04 frame="ACQ_NKE_01L,0,1.000,1,1,0,0,1,1,10,0,500,1.0,100,10,0,1000,0,40,1
            <ACQ_CONF_05 frame="ACQ_NKE_20H,0,1.000,1,1,0,0,1,1,10,2,500,1.0,10,10,0,1000,0,40,la
            <ACQ_CONF_06 frame="ACQ_NKE_20L,0,1.000,1,1,0,0,1,1,10,2,500,1.0,100,10,0,1000,0,40,1
            <ACQ_CONF_07 frame="ACQ_NKE_21H,0,1.000,1,1,0,0,1,1,10,2,500,1.0,10,10,0,1000,0,40,la
            <ACQ_CONF_08 frame="ACQ_NKE_21L,0,1.000,1,1,0,0,1,1,10,2,500,1.0,100,10,0,1000,0,40,1
            <ACQ_CONF_09 frame="ACQ_NKE_CUST_1,0,1.000,1,1,0,0,1,1,10,2,500,1.0,15,10,0,1000,0,40
            <ACQ_CONF_10 frame="ACQ_NKE_CUST_2,0,1.000,1,1,0,0,1,1,10,1,500,1.0,30,10,0,1000,0,40
        </SENSOR_UVP6>
        <SENSOR_DO>
            <SENSOR SN="03014" Model="DO4330"/>
            <PHASE_COEFF c0="9.500000e-02"/>
            <SVU_FOIL_COEFF c0="2.749372e-03" c1="1.217100e-04" c2="2.062590e-06" c3="1.655341e+(
        </SENSOR_DO>
        <SENSOR_OCR>
            <SENSOR SN="00184" Model="OCR504"/>
            <CHANNEL_01 a0="2.14766538910e+09" a1="1.63699685504e-07" im="1.161e+00"/>
            <CHANNEL_02 a0="2.14754852610e+09" a1="2.00131764196e-07" im="1.368e+00"/>
            <CHANNEL_03 a0="2.14742382370e+09" a1="2.04019168366e-07" im="1.365e+00"/>
            <CHANNEL_04 a0="2.14745155870e+09" a1="3.03210835119e-06" im="1.359e+00"/>
        </SENSOR_OCR>
        <SENSOR_ECO>
            <SENSOR SN="02345" Model="ECO3"/>
            <CHANNEL_01 sf="7.200e-03" dc="47"/>
            <CHANNEL_02 sf="2.029e-06" dc="43"/>
            <CHANNEL_03 sf="8.720e-02" dc="30"/>
        </SENSOR_ECO>
        <SENSOR_SUNA>
            <SENSOR SN="00555" Model="SUNA-V2" Spectrum="Output pixels 38-77"/>
            <SUNA_BOARD Firmware="2.2.13"/>
            <SPECTROMETER spintper="400"/>
        </SENSOR_SUNA>
        <SENSOR_SBE41>
            <SENSOR SN="08959" Model="SBE41-CP"/>
            <SENSOR_PRESSURE SN="004978241"/>
        </SENSOR_SBE41>
    </SENSORS>
</FLOAT>
```

6. Sensor data files

The system can generate sensor data files under three formats:

- Text format (*.csv)
- Standard binary format (*.hex)
- Extended binary format (*.hex)

6.1. Transmission of sensor data

The various sensor data files generated are named using the format "xxxx_ccc_mm_ssssss.ext", with:

- "xxxx": float's hexadecimal serial number (4 characters)
- "ccc": cycle number (3 characters)
- "mm": pattern number (2 characters)
- "sssss": sensor ID (N characters, e.g. "sbe41")
- "ext": file extension

All data from a sensor are saved in a unique data file associated to the cycle/pattern.

6.2. ID tags

All files are organised in sections using ID tags for the phase and processing type.

6.2.1. Navigation phase identification

At every change of navigation phase, an ID string is inserted. The various ASCII strings are as follows:

- **[DESCENT]**: Data from the descent phase, from the surface to the drift depth
- **[PARK]**: Data from the drift phase
- **[DEEP_PROFILE]**: Data from the descent phase, from the drift depth to the measurement depth
- **[SHORT_PARK]**: Data from the drift phase, from the drift depth to the measurement depth
- **[ASCENT]**: Data from the ascent phase
- **[SURFACE]**: Data from the surface phase

6.2.2. Processing type identification

At every change of phase or processing area, an ID string for the processing type is inserted. The various ASCII strings are as follows:

- **(RW)**: For raw data
- **(DW)**: For decimated raw data
- **(AM)**: For arithmetic mean
- **(SD)**: For standard deviation
- **(MD)**: For median
- **(SS)**: For subsurface point

Several processing types can follow one another. The combinations are as follows:

- (RW)
- (DW)
- (AM)
- (AM)(SD)
- (AM)(MD)
- (AM)(SD)(MD)
- (SS)

6.3. Recording in text format

Spreadsheet format with the possibility of choosing the decimal separator, the column separator as well as the timestamping format can be selected.

```
[DESCENT]
(AM) (SD) (MD)
2015-06-15 08:34:51;4.90;17.4640;35.798;0.0000;0.0000;4.90;17.4640;35.798
2015-06-15 08:34:51;5.50;17.4600;35.797;0.0030;0.0000;5.50;17.4600;35.797
2015-06-15 08:34:51;6.40;17.4530;35.797;0.0030;0.0000;6.40;17.4530;35.797
2015-06-15 08:34:51;7.40;17.4470;35.796;0.0030;0.0000;7.40;17.4500;35.797
2015-06-15 08:34:51;8.50;17.4380;35.796;0.0030;0.0000;8.50;17.4360;35.796
2015-06-15 08:34:51;9.50;17.4320;35.796;0.0030;0.0000;9.50;17.4290;35.796
```

6.4.Recording in binary format

6.4.1. Encoding format

The data is saved in "little endian" format with byte alignment objects:

- **BYTE** - char (1 byte)
- **USHORTINT** - unsigned short integer (2 bytes)
- **SHORTINT** - short integer (2 bytes)
- **LONGINT** - long integer (4 bytes)
- **EPOCH** – absolute timestamping (4 bytes) - Unix Epoch format - January 1st, 1970 at 0:00
- **FLOAT** - floating (4 bytes - float) – IEEE-754 format

6.4.2. File structure

Each file begins with an encoding identifying byte:

- 0x01: SBE41 sensor - Extended format
- 0x02: SBE41 sensor - Standard format
- 0x03: DO sensor
- 0x04: OCR504 sensor (4 channels)
- 0x05: OCR507 sensor (7 channels)
- 0x06: OCR507-IR sensor (14 channels)
- 0x07: ECO1 sensor (1 channel)
- 0x08: ECO2 sensor (2 channels)
- 0x09: ECO3 sensor (3 channels)
- 0x0A: CROVER sensor
- 0x0B: SBEPH sensor
- 0x0C: SUNA sensor (45 outputs spectrum)
- 0x0D: SUNA sensor (90 outputs spectrum)
- 0x0E: UVP6 sensor (LPM data)
- 0x0F: None
- 0x10: None
- 0x11: UVP6 sensor (BLACK data)
- 0x12: ECO1v2 sensor (1 channel)
- 0x13: ECO2v2 sensor (2 channels)
- 0x14: ECO3v2 sensor (3 channels)
- 0x15: ECO4v2 sensor (4 channels)
- 0x16: EXTTRIG sensor
- 0x17: RAMSES sensor
- 0x18: OPUS sensor (LIGHT data)
- 0x19: OPUS sensor (BLACK data)
- 0x1A: MPE sensor
- 0x1B: UVP6 sensor (LPMv2 data)
- 0x1C: UVP6 sensor (TAXOv2 data)
- 0x1D: UVP sensor (BLACKv2 data)

This is followed by groups of recordings identified by the tags.

Example: SBE41 standard format file, descent phase

```
00000000   01 5b 44 45   53 43 45 4e   54 5d 28 44   57 29 cb 65   .[DESCENT](DW)Ëe
00000010   e4 5b 00 00   12 04 c7 57   d6 8b 36 55   00 1e 04 c0   ä[....ÇWÖ‹6U...À
00000020   57 d6 8b 45   56 00 29 04   b2 57 d5 8b   13 80 00 36   WÖ‹EV.).ªWÖ‹.€.6
00000030   04 ab 57 d4   8b 62 80 00   41 04 a4 57   d4 8b 61 80   .«WÔ‹b€.A.¤WÔ‹a€
00000040   00 4f 04 9d   57 d4 8b 50   80 00 5d 04   8e 57 d2 8b   .O. WÔ‹P€.].ŽWÒ‹
00000050   38 81 00 68   04 87 57 d1   8b 67 aa 00   74 04 80 57   8 .h.‡WÑ‹gª.t.€W
```

Note: In Iridium RUDICS transmission, files can be supplemented by padding bytes (0x1A). These bytes must not be decoded. Each file can end with a sequence of 0 to 1023 padding bytes.

6.4.3. Timestamping

Records can be timestamped with absolute timestamps (Unix Epoch format) or relative timestamps since a reference date.

Absolute timestamping is used for raw data records in parking phase (where the delay between records can be greater than hours). Data is encoded as follows:

- **Timestamp** absolute encoding (EPOCH)

Relative timestamping is used for the others records. The reference date is saved after the navigation phase tag. The following records use an offset (count in seconds) from this reference time. Data is encoded as follows:

- **Timestamp** offset in seconds (unsigned integer) – code = value - reference time

Example: Relative timestamping encoding

```
00000000   01 5b 44 45   53 43 45 4e   54 5d 28 44   57 29 cb 65   .[DESCENT](DW)Ëe
00000010   e4 5b 00 00   12 04 c7 57   d6 8b 36 55   00 1e 04 c0   ä[....ÇWÖ‹6U...À
00000020   57 d6 8b 45   56 00 29 04   b2 57 d5 8b   13 80 00 36   WÖ‹EV.).ªWÖ‹.€.6
00000030   04 ab 57 d4   8b 62 80 00   41 04 a4 57   d4 8b 61 80   .«WÔ‹b€.A.¤WÔ‹a€
00000040   00 4f 04 9d   57 d4 8b 50   80 00 5d 04   8e 57 d2 8b   .O. WÔ‹P€.].ŽWÒ‹
00000050   38 81 00 68   04 87 57 d1   8b 67 aa 00   74 04 80 57   8 .h.‡WÑ‹gª.t.€W
```

Timestamp   = 1541694923 (0x5BE465CB) + 0 sec (0x0000) => 2018-11-08 16:35:23

6.5. SBE41 sensor

6.5.1. Data encoding

Data is encoded as follows:

- **Timestamping** of each record
- **Pressure** in cbar and +100 dbar offset (unsigned integer) – code = (value + 100.0) * 10.0
- **Temperature** in m°C and +5.0°C offset (unsigned integer) – code = (value + 5.0) * 1000.0
- **Salinity** in mpsu (unsigned integer) – code = value * 1000.0
- **Temperature standard deviation** in m°C (signed integer) – code = value * 1000.0
- **Salinity standard deviation** in mpsu (signed integer) – code = value * 1000.0

6.5.2. Standard binary format

During the "descent" and "ascent" navigation phases, the first record of each processing area is timestamped in absolute value (reference date), then the recordings for the next records are timestamped in relative value by encoding the date in relation to the reference date (deviation in seconds).

During the "drift" phases, all records are timestamped in absolute value.

The recording structures are as follows:

Subsurface - (SS)
```
struct
 {
  unsigned long int uliDateTime;
  unsigned short int uiPressure;
  unsigned short int uiATemperature;
  unsigned short int uiSalinity;
 }
 tSSStd;
```

Subsurface data encoding (ascent)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	EPOCH	-	1 sec	4
Subsurface record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Salinity	SHORTINT	0.0 to +50.0 psu	0.001 psu	2
				10

Raw data (drift) – (RW) or (DW)

```
struct
 {
  unsigned long int uliDateTime;
  unsigned short int uiAveragePressure;
  unsigned short int uiAverageTemperature;
  unsigned short int uiAverageSalinity;
 }
 tRStdPark;
```

Raw data encoding (park phase)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	EPOCH	-	1 sec	4
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Salinity	SHORTINT	0.0 to +50.0 psu	0.001 psu	2
				10

Raw data (navigation) – (RW) or (DW)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  unsigned short int uiAverageTemperature;
  unsigned short int uiAverageSalinity;
 }
 tRStdNav;
```

Raw data encoding (navigation phase)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Salinity	SHORTINT	0.0 to +50.0 psu	0.001 psu	2
				8

Averaged data – (AM)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  unsigned short int uiAverageTemperature;
  unsigned short int uiAverageSalinity;
 }
 tMStd;
```

Average data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Salinity	SHORTINT	0.0 to +50.0 psu	0.001 psu	2
				8

Averaged data and standard deviation – (AM)(SD)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  unsigned short int uiAverageTemperature;
  unsigned short int uiAverageSalinity;
  signed char cStdDeviationTemperature;
  signed char cStdDeviationSalinity;
 }
 tMECStd;
```

Average + standard deviation data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Salinity	SHORTINT	0.0 to +50.0 psu	0.001 psu	2
Standard deviation record				
Temperature STD	BYTE	-0.128 to +0.127°C	0.001°C	1
Salinity STD	BYTE	-0.128 to +0.127 psu	0.001 psu	1
				10

Averaged data and median – (AM)(MD)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  unsigned short int uiAverageTemperature;
  unsigned short int uiAverageSalinity;
  unsigned short int uiMedianPressure;
  unsigned short int uiMedianTemperature;
  unsigned short int uiMedianSalinity;
 }
 tMMStd;
```

Average + median data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Salinity	SHORTINT	0.0 to +50.0 psu	0.001 psu	2
Median record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Salinity	SHORTINT	0.0 to +50.0 psu	0.001 psu	2
				14

Averaged data, standard deviation and median – (AM)(SD)(MD)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  unsigned short int uiAverageTemperature;
  unsigned short int uiAverageSalinity;
  signed char cStdDeviationTemperature;
  signed char cStdDeviationSalinity;
  unsigned short int uiMedianPressure;
  unsigned short int uiMedianTemperature;
  unsigned short int uiMedianSalinity;
 }
 tMECMStd;
```

Average + standard deviation + median data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Salinity	SHORTINT	0.0 to +50.0 psu	0.001 psu	2
Standard deviation record				
Temperature STD	BYTE	-0.128 to +0.127°C	0.001°C	1
Salinity STD	BYTE	-0.128 to +0.127 psu	0.001 psu	1
Median record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Salinity	SHORTINT	0.0 to +50.0 psu	0.001 psu	2
				16

Example:
[DESCENT]
(DW)
2018-11-08 16:35:23,4.2,17.471,35.798
2018-11-08 16:36:48,5.4,17.464,35.798


```
00000000   01 5b 44 45   53 43 45 4e   54 5d 28 44   57 29 cb 65    .[DESCENT] (DW)Ëe
00000010   e4 5b 00 00   12 04 c7 57   d6 8b 55 00   1e 04 c0 57    ä[....ÇWÖ‹U...ÀW
00000020   d6 8b 56 00   29 04 b2 57   d5 8b 13 80   00 36 04 ab    Ö‹V.).²WÖ‹.€.6.«
00000030   57 d4 8b 62   80 00 41 04   a4 57 d4 8b   61 80 00 4f    WÔ‹b€.A.¤WÔ‹a€.O
00000040   04 9d 57 d4   8b 50 80 00   5d 04 8e 57   d2 8b 38 81    . WÔ‹P€.].ŽWÒ‹8
```

Timestamp 1   = 1541694923 (0x5BE465CB) + 0 sec (0x0000) => 2018-11-08 16:35:23
Pressure 1   = 1042 (0x0412) => ((1042 / 10.0) – 100.0) = 4.2 dbar
Temperature 1 = 22471 (0x57C7) => ((22471 / 1000.0) – 5.0) = 17.471°C
Salinity 1   = 35798 (0xD68B) => (35798 / 1000.0) = 35.798 psu
Timestamp 2   = Timestamp 1 + 85 sec (0x0055) => 2018-11-08 16:36:48

…

6.5.3. Extended binary format

Advantages of this format compared to the standard version:

- Improved resolution of recordings (pressure and temperature)

During the "descent" and "ascent" navigation phases, the first record of each processing area is timestamped in absolute value (reference date), then the recordings for the next records are timestamped in relative value by encoding the date in relation to the reference date (deviation in seconds).

During the "drift" phases, all records are timestamped in absolute value.

The resolution extension for pressure and temperature measurements is encoded on a shared byte using masks, as follows:

- Pressure extension (0.01 dbar) = value & 0xF0
- Temperature extension (0.1 m°C) = value & 0x0F

The available recording structures are as follows:

Subsurface – (SS)

```
struct
{
 unsigned long int uliDateTime;
 unsigned short int uiPressure;
 unsigned short int uiTemperature;
 unsigned short int uiSalinity;
 unsigned char ucPTExtra;
}
 tSSExt;
```

Subsurface data encoding (ascent)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	EPOCH	-	1 sec	4
Subsurface record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Salinity	SHORTINT	0.0 to +50.0 psu	0.001 psu	2
Pressure extra	BYTE_H	0.00 to 0.09 dbar	0.01 dbar	1
Temperature extra	BYTE_L	0.0000 to 0.0009°C	0.0001°C	
				11

Raw data (park) – (RW) or (DW)

```
struct
 {
  unsigned long int uliDateTime;
  unsigned short int uiAveragePressure;
  unsigned short int uiAverageTemperature;
  unsigned short int uiAverageSalinity;
  unsigned char ucAveragePTExtra;
 }
 tRExtPark;
```

Raw data encoding (park phase)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	EPOCH	-	1 sec	4
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Salinity	SHORTINT	0.0 to +50.0 psu	0.001 psu	2
Pressure extra	BYTE_H	0.00 to 0.09 dbar	0.01 dbar	1
Temperature extra	BYTE_L	0.0000 to 0.0009°C	0.0001°C	
				11

Raw data (navigation) – (RW) or (DW)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  unsigned short int uiAverageTemperature;
  unsigned short int uiAverageSalinity;
  unsigned char ucAveragePTExtra;
 }
 tRExtNav;
```

Raw data encoding (navigation phase)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Salinity	SHORTINT	0.0 to +50.0 psu	0.001 psu	2
Pressure extra	BYTE_H	0.00 to 0.09 dbar	0.01 dbar	1
Temperature extra	BYTE_L	0.0000 to 0.0009°C	0.0001°C	
				9

Averaged data – (AM)

struct

 {

  unsigned short int uiDateTimeDelta;

  unsigned short int uiAveragePressure;

  unsigned short int uiAverageTemperature;

  unsigned short int uiAverageSalinity;

  unsigned char ucAveragePTExtra;

 }

 tMExt;

<table>
<tr><th colspan="5">Average data encoding</th></tr>
<tr><th>Field</th><th>Format</th><th>Range</th><th>Resolution</th><th>Size (Byte)</th></tr>
<tr><td>Timestamp</td><td>SHORTINT</td><td>0 to +65535 sec</td><td>1 sec</td><td>2</td></tr>
<tr><td colspan="5">Average record</td></tr>
<tr><td>Pressure</td><td>SHORTINT</td><td>-100 to +2500 dbar</td><td>0.1 dbar</td><td>2</td></tr>
<tr><td>Temperature</td><td>SHORTINT</td><td>-5.0 to +40.0°C</td><td>0.001°C</td><td>2</td></tr>
<tr><td>Salinity</td><td>SHORTINT</td><td>0.0 to +50.0 psu</td><td>0.001 psu</td><td>2</td></tr>
<tr><td>Pressure extra</td><td>BYTE_H</td><td>0.00 to 0.09 dbar</td><td>0.01 dbar</td><td>1</td></tr>
<tr><td>Temperature extra</td><td>BYTE_L</td><td>0.0000 to 0.0009°C</td><td>0.0001°C</td><td></td></tr>
<tr><td></td><td></td><td></td><td></td><td>9</td></tr>
</table>

Averaged data and standard deviation – (AM)(SD)

struct

 {

  unsigned short int uiDateTimeDelta;

  unsigned short int uiAveragePressure;

  unsigned short int uiAverageTemperature;

  unsigned short int uiAverageSalinity;

  unsigned char ucAveragePTExtra;

  signed char cStdDeviationTemperature;

  signed char cStdDeviationSalinity;

 }

 tMECExt;

<table>
<tr><th colspan="5">Average + standard deviation data encoding</th></tr>
<tr><th>Field</th><th>Format</th><th>Range</th><th>Resolution</th><th>Size (Byte)</th></tr>
<tr><td>Timestamp</td><td>SHORTINT</td><td>0 to +65535 sec</td><td>1 sec</td><td>2</td></tr>
<tr><td colspan="5">Average record</td></tr>
<tr><td>Pressure</td><td>SHORTINT</td><td>-100 to +2500 dbar</td><td>0.1 dbar</td><td>2</td></tr>
<tr><td>Temperature</td><td>SHORTINT</td><td>-5.0 to +40.0°C</td><td>0.001°C</td><td>2</td></tr>
<tr><td>Salinity</td><td>SHORTINT</td><td>0.0 to +50.0 psu</td><td>0.001 psu</td><td>2</td></tr>
<tr><td>Pressure extra</td><td>BYTE_H</td><td>0.00 to 0.09 dbar</td><td>0.01 dbar</td><td>1</td></tr>
<tr><td>Temperature extra</td><td>BYTE_L</td><td>0.0000 to 0.0009°C</td><td>0.0001°C</td><td></td></tr>
</table>

Standard deviation record				
Temperature STD	BYTE	-0.128 to +0.127°C	0.001°C	1
Salinity STD	BYTE	-0.128 to +0.127 psu	0.001 psu	1
				11

Averaged data and median – (AM)(MD)

struct
{
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  unsigned short int uiAverageTemperature;
  unsigned short int uiAverageSalinity;
  unsigned char ucAveragePTExtra;
  unsigned short int uiMedianPressure;
  unsigned short int uiMedianTemperature;
  unsigned short int uiMedianSalinity;
  unsigned char ucMedianPTExtra;
}
tMMExt;

Average + median data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Salinity	SHORTINT	0.0 to +50.0 psu	0.001 psu	2
Pressure extra	BYTE_H	0.00 to 0.09 dbar	0.01 dbar	1
Temperature extra	BYTE_L	0.0000 to 0.0009°C	0.0001°C	
Median record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Salinity	SHORTINT	0.0 to +50.0 psu	0.001 psu	2
Pressure extra	BYTE_H	0.00 to 0.09 dbar	0.01 dbar	1
Temperature extra	BYTE_L	0.0000 to 0.0009°C	0.0001°C	
				16

Averaged data, standard deviation and median – (AM)(SD)(MD)

```
struct
{
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  unsigned short int uiAverageTemperature;
  unsigned short int uiAverageSalinity;
  unsigned char ucAveragePTExtra;
  signed char cStdDeviationTemperature;
  signed char cStdDeviationSalinity;
  unsigned short int uiMedianPressure;
  unsigned short int uiMedianTemperature;
  unsigned short int uiMedianSalinity;
  unsigned char ucMedianPTExtra;
}
tMECMExt;
```

Average + standard deviation + median data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Salinity	SHORTINT	0.0 to +50.0 psu	0.001 psu	2
Pressure extra	BYTE_H	0.00 to 0.09 dbar	0.01 dbar	1
Temperature extra	BYTE_L	0.0000 to 0.0009°C	0.0001°C	
Standard deviation record				
Temperature STD	BYTE	-0.128 to +0.127°C	0.001°C	1
Salinity STD	BYTE	-0.128 to +0.127 psu	0.001 psu	1
Median record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Salinity	SHORTINT	0.0 to +50.0 psu	0.001 psu	2
Pressure extra	BYTE_H	0.00 to 0.09 dbar	0.01 dbar	1
Temperature extra	BYTE_L	0.0000 to 0.0009°C	0.0001°C	
				18

Example:

[DESCENT]
(DW)
2018-11-08 16:35:23,4.23,17.4716,35.798
2018-11-08 16:36:48,5.44,17.4645,35.798

```
00000000 | 01 5b 44 45   53 43 45 4e   54 5d 28 44   57 29 cb 65   .[DESCENT](DW)Ëe
00000010 | e4 5b 00 00   12 04 c7 57   d6 8b 36 55   00 1e 04 c0   ä[....ÇWÖ‹6U...À
00000020 | 57 d6 8b 45   56 00 29 04   b2 57 d5 8b   13 80 00 36   WÖ‹EV.).²WÕ‹.€.6
00000030 | 04 ab 57 d4   8b 62 80 00   41 04 a4 57   d4 8b 61 80   .«WÔ‹b€.A.¤WÔ‹a€
00000040 | 00 4f 04 9d   57 d4 8b 50   80 00 5d 04   8e 57 d2 8b   .O. WÔ‹P€.].ŽWÒ‹
00000050 | 38 81 00 68   04 87 57 d1   8b 67 aa 00   74 04 80 57   8 .h.‡WÑ‹g ª.t.€W
```

Timestamp 1 = 1541694923 (0x5BE465CB) + 0 sec (0x0000) => 2018-11-08 16:35:23
Pressure 1 = 1042 (0x0412) + 0.03 dbar (0x3_) => ((1042 / 10.0) − 100.0) + 0.03 = 4.23 dbar
Temperature 1 = 22471 (0x57C7) + 0.0006°C (0x_6) => ((22471 / 1000.0) − 5.0) + 0.006 = 17.4716°C
Salinity 1 = 35798 (0xD68B) => (35798 / 1000.0) = 35.798 psu
Timestamp 2 = Timestamp 1 + 85 sec (0x0055) => 2018-11-08 16:36:48

…

6.6. DO sensor

Data is encoded as follows:

- **Timestamping** of each record
- **Pressure** in cbar and +100 dbar offset (unsigned integer) – code = (value + 100.0) * 10.0
- **Phase** in degrees (float) – code = value
- **Temperature** in m°C and +5.0°C offset (unsigned integer) – code = (value + 5.0) * 1000.0
- **Phase standard deviation** in degrees (signed integer) – code = value * 1000.0
- **Temperature standard deviation** in m°C (signed integer) – code = value * 1000.0

During the "descent" and "ascent" navigation phases, the first record of each processing area is timestamped in absolute value (reference date), then the recordings for the next records are timestamped in relative value by encoding the date in relation to the reference date (deviation in seconds).

During the "drift" phases, all records are timestamped in absolute value.

The available recording structures are as follows:

Raw data (park) – (RW) or (DW)

```
struct
 {
  unsigned long int uliDateTime;
  unsigned short int uiPressure;
  float fC1RPhase;
  float fC2RPhase;
  unsigned short int uiTemperature;
 }
 tRPark;
```

Raw data encoding (park)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	EPOCH	-	1 sec	4
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
C1 Phase	FLOAT	-90.0 to +90.0 deg	IEEE float	4
C2 Phase	FLOAT	-90.0 to +90.0 deg	IEEE float	4
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
				16

Raw data (navigation) – (RW) or (DW)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiPressure;
  float fC1RPhase;
  float fC2RPhase;
  unsigned short int uiTemperature;
 }
 tRNav;
```

Raw data encoding (navigation)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
C1 Phase	FLOAT	-90.0 to +90.0 deg	IEEE float	4
C2 Phase	FLOAT	-90.0 to +90.0 deg	IEEE float	4
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
				14

Averaged data – (AM)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  float fAverageC1RPhase;
  float fAverageC2RPhase;
  unsigned short int uiAverageTemperature;
 }
 tM;
```

Average data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
C1 Phase	FLOAT	-90.0 to +90.0 deg	IEEE float	4
C2 Phase	FLOAT	-90.0 to +90.0 deg	IEEE float	4
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
				14

Averaged data and standard deviation – (AM)(SD)

```
struct
{
 unsigned short int uiDateTimeDelta;
 unsigned short int uiAveragePressure;
 float fAverageC1RPhase;
 float fAverageC2RPhase;
 unsigned short int uiAverageTemperature;
 signed short int iStdDeviationC1RPhase;
 signed short int iStdDeviationC2RPhase;
 signed char cStdDeviationTemperature;
}
tMEC;
```

Average + standard deviation data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
C1 Phase	FLOAT	-90.0 to +90.0 deg	IEEE float	4
C2 Phase	FLOAT	-90.0 to +90.0 deg	IEEE float	4
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Standard deviation record				
C1 Phase	SHORTINT	-32.768 to +32.767 deg	0.001 deg	2
C2 Phase	SHORTINT	-32.768 to +32.767 deg	0.001 deg	2
Temperature	BYTE	-0.128 to +0.127°C	0.001°C	1
				19

Averaged data and median – (AM)(MD)

```
struct
{
 unsigned short int uiDateTimeDelta;
 unsigned short int uiAveragePressure;
 float fAverageC1RPhase;
 float fAverageC2RPhase;
 unsigned short int uiAverageTemperature;
 unsigned short int uiMedianPressure;
 float fMedianC1RPhase;
 float fMedianC2RPhase;
 unsigned short int uiMedianTemperature;
}
tMM;
```

Average + median data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
C1 Phase	FLOAT	-90.0 to +90.0 deg	IEEE float	4
C2 Phase	FLOAT	-90.0 to +90.0 deg	IEEE float	4
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Median record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
C1 Phase	FLOAT	-90.0 to +90.0 deg	IEEE float	4
C2 Phase	FLOAT	-90.0 to +90.0 deg	IEEE float	4
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
				26

Averaged data, standard deviation and median – (AM)(SD)(MD)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  float fAverageC1RPhase;
  float fAverageC2RPhase;
  unsigned short int uiAverageTemperature;
  signed short int iStdDeviationC1RPhase;
  signed short int iStdDeviationC2RPhase;
  signed char cStdDeviationTemperature;
  unsigned short int uiMedianPressure;
  float fMedianC1RPhase;
  float fMedianC2RPhase;
  unsigned short int uiMedianTemperature;
 }
 tMECM;
```

Average + standard deviation + median data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
C1 Phase	FLOAT	-90.0 to +90.0 deg	IEEE float	4
C2 Phase	FLOAT	-90.0 to +90.0 deg	IEEE float	4
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Standard deviation record				
C1 Phase	SHORTINT	-32.768 to +32.767 deg	0.001 deg	2
C2 Phase	SHORTINT	-32.768 to +32.767 deg	0.001 deg	2
Temperature	BYTE	-0.128 to +0.127°C	0.001°C	1
Median record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
C1 Phase	FLOAT	-90.0 to +90.0 deg	IEEE float	4
C2 Phase	FLOAT	-90.0 to +90.0 deg	IEEE float	4
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
				31

Example:
[DESCENT]
(DW)
2018-11-08 16:13:01,3.7,38.181,8.958,25.66
2018-11-08 16:13:10,5.2,38.165,8.955,25.65

Timestamp 1   = 1541693581 (0x5BE4608D) + 0 sec (0x0000) => 2018-11-08 16:13:01
Pressure 1   = 1037 (0x040D) => ((1037 / 10.0) − 100.0) = 3.7 dbar
[...]
Temperature 1 = 30660 (0x77C4) => ((30660 / 1000.0) − 5.0) = 25.66°C
Timestamp 2   = Timestamp 1 + 9 sec (0x0009) => 2018-11-08 16:13:10
…

6.7. OCR sensor

Data is encoded as follows:

- **Timestamping** of each record
- **Pressure** in cbar and +100 dbar offset (unsigned integer) – code = (value + 100.0) * 10.0
- **Channel count** (unsigned long int) – code = value
- **Channel count standard deviation** (signed long int) – code = value

Data record can be composed of counts from 4, 7 or 14 channels (depending on the sensor's configuration).

During the "descent" and "ascent" navigation phases, the first record of each processing area is timestamped in absolute value (reference date), then the recordings for the next records are timestamped in relative value by encoding the date in relation to the reference date (deviation in seconds).

During the "drift" phases, all records are timestamped in absolute value.

The available recording structures are as follows:

Raw data (park) – (RW) or (DW)

```
struct
 {
  unsigned long int uliDateTime;
  unsigned short int uiPressure;
  unsigned long int uliCountChannel1;
  unsigned long int uliCountChannel2;
  [...]
  unsigned long int uliCountChannelN;
 }
 tRPark;
```

4 channels - Raw data encoding (park)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	EPOCH	-	1 sec	4
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	LONGINT	0 to +4294967295	1	4
Channel 2 count	LONGINT	0 to +4294967295	1	4
Channel 3 count	LONGINT	0 to +4294967295	1	4
Channel 4 count	LONGINT	0 to +4294967295	1	4
				22

Raw data (navigation) – (RW) or (DW)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiPressure;
  unsigned long int uliCountChannel1;
  unsigned long int uliCountChannel2;
  [...]
  unsigned long int uliCountChannelN;
 }
 tRNav;
```

4 channels - Raw data encoding (navigation)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	LONGINT	0 to +4294967295	1	4
Channel 2 count	LONGINT	0 to +4294967295	1	4
Channel 3 count	LONGINT	0 to +4294967295	1	4
Channel 4 count	LONGINT	0 to +4294967295	1	4
				20

Averaged data – (AM)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  unsigned long int uliAverageCountChannel1;
  unsigned long int uliAverageCountChannel2;
  [...]
  unsigned long int uliAverageCountChannelN;
 }
 tM;
```

4 channels - Average data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	LONGINT	0 to +4294967295	1	4
Channel 2 count	LONGINT	0 to +4294967295	1	4
Channel 3 count	LONGINT	0 to +4294967295	1	4
Channel 4 count	LONGINT	0 to +4294967295	1	4
				20

Averaged data and standard deviation – (AM)(SD)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  unsigned long int uliAverageCountChannel1;
  unsigned long int uliAverageCountChannel2;
  [...]
  unsigned long int uliAverageCountChannelN;
  signed long int liStdDeviationCountChannel1;
  signed long int liStdDeviationCountChannel2;
  [...]
  signed long int liStdDeviationCountChannelN;
 }
 tMEC;
```

4 channels - Average + standard deviation data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	LONGINT	0 to +4294967295	1	4
Channel 2 count	LONGINT	0 to +4294967295	1	4
Channel 3 count	LONGINT	0 to +4294967295	1	4
Channel 4 count	LONGINT	0 to +4294967295	1	4
Standard deviation record				
Channel 1 count	LONGINT	-2147483648 to +2147483647	1	4
Channel 2 count	LONGINT	-2147483648 to +2147483647	1	4
Channel 3 count	LONGINT	-2147483648 to +2147483647	1	4
Channel 4 count	LONGINT	-2147483648 to +2147483647	1	4
				34

Averaged data and median – (AM)(MD)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  unsigned long int uliAverageCountChannel1;
  unsigned long int uliAverageCountChannel2;
  [...]
  unsigned long int uliAverageCountChannelN;
  unsigned short int uiMedianPressure;
  unsigned long int uliMedianCountChannel1;
  unsigned long int uliMedianCountChannel2;
  [...]
  unsigned long int uliMedianCountChannelN;
 }
 tMM;
```

4 channels - Average + median data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	LONGINT	0 to +4294967295	1	4
Channel 2 count	LONGINT	0 to +4294967295	1	4
Channel 3 count	LONGINT	0 to +4294967295	1	4
Channel 4 count	LONGINT	0 to +4294967295	1	4
Median record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	LONGINT	0 to +4294967295	1	4
Channel 2 count	LONGINT	0 to +4294967295	1	4
Channel 3 count	LONGINT	0 to +4294967295	1	4
Channel 4 count	LONGINT	0 to +4294967295	1	4
				38

Averaged data, standard deviation and median – (AM)(SD)(MD)

```
struct
{
 unsigned short int uiDateTimeDelta;
 unsigned short int uiAveragePressure;
 unsigned long int uliAverageCountChannel1;
 unsigned long int uliAverageCountChannel2;
 [...]
 unsigned long int uliAverageCountChannelN;
 signed long int liStdDeviationCountChannel1;
 signed long int liStdDeviationCountChannel2;
 [...]
 signed long int liStdDeviationCountChannelN;
 unsigned short int uiMedianPressure;
 unsigned long int uliMedianCountChannel1;
 unsigned long int uliMedianCountChannel2;
 [...]
 unsigned long int uliMedianCountChannelN;
}
tMECM;
```

4 channels - Average + standard deviation + median data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	LONGINT	0 to +4294967295	1	4
Channel 2 count	LONGINT	0 to +4294967295	1	4
Channel 3 count	LONGINT	0 to +4294967295	1	4
Channel 4 count	LONGINT	0 to +4294967295	1	4
Standard deviation record				
Channel 1 count	LONGINT	-2147483648 to +2147483647	1	4
Channel 2 count	LONGINT	-2147483648 to +2147483647	1	4
Channel 3 count	LONGINT	-2147483648 to +2147483647	1	4
Channel 4 count	LONGINT	-2147483648 to +2147483647	1	4
Median record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	LONGINT	0 to +4294967295	1	4
Channel 2 count	LONGINT	0 to +4294967295	1	4
Channel 3 count	LONGINT	0 to +4294967295	1	4
Channel 4 count	LONGINT	0 to +4294967295	1	4
				54

Example:

[DESCENT]
(DW)
2018-11-08 16:13:01,3.7,2147299913,2147399789,2147931867,2147056502
2018-11-08 16:13:07,4.2,2147302930,2147406436,2147929755,2147059858

Timestamp 1   = 1541693581 (0x5BE4608D) + 0 sec (0x0000) => 2018-11-08 16:13:01
Pressure 1   = 1037 (0x040D) => ((1037 / 10.0) – 100.0) = 3.7 dbar
Count 1   = 2147299913 (0x7FFD3249)
[...]
Timestamp 2   = Timestamp 1 + 6 sec (0x0006) => 2018-11-08 16:13:07
...

6.8. ECO sensor

Data is encoded as follows:

- **Timestamping** of each record
- **Pressure** in cbar and +100 dbar offset (unsigned integer) – code = (value + 100.0) * 10.0
- **Channel count** (signed short int) – code = value
- **Channel count standard deviation** (signed char) – code = value

Data record can be composed of counts from 1 to 3 channels (depending on the sensor's configuration).

During the "descent" and "ascent" navigation phases, the first record of each processing area is timestamped in absolute value (reference date), then the recordings for the next records are timestamped in relative value by encoding the date in relation to the reference date (deviation in seconds).

During the "drift" phases, all records are timestamped in absolute value.

The available recording structures are as follows:

Raw data (park) – (RW) or (DW)
```
struct
{
 unsigned long int uliDateTime;
 unsigned short int uiPressure;
 signed short int iCountChannel1;
[…]
 signed short int iCountChannelN;
}
 tRPark;
```

3 channels - Raw data encoding (park)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	EPOCH	-	1 sec	4
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	SHORTINT	-64 to +4130	1	2
Channel 2 count	SHORTINT	-64 to +4130	1	2
Channel 3 count	SHORTINT	-64 to +4130	1	2
				12

Raw data (navigation) – (RW) or (DW)

```
struct
{
 unsigned short int uiDateTimeDelta;
 unsigned short int uiPressure;
 signed short int iCountChannel1;
 [...]
 signed short int iCountChannelN;
}
 tRNav;
```

3 channels - Raw data encoding (navigation)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	-	1 sec	2
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	SHORTINT	-64 to +4130	1	2
Channel 2 count	SHORTINT	-64 to +4130	1	2
Channel 3 count	SHORTINT	-64 to +4130	1	2
				10

Averaged data – (AM)

```
struct
{
 unsigned short int uiDateTimeDelta;
 unsigned short int uiAveragePressure;
 signed short int iAverageCountChannel1;
 [...]
 signed short int iAverageCountChannelN;
}
 tM;
```

3 channels - Average data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	SHORTINT	-64 to +4130	1	2
Channel 2 count	SHORTINT	-64 to +4130	1	2
Channel 3 count	SHORTINT	-64 to +4130	1	2
				10

Averaged data and standard deviation – (AM)(SD)

```
struct
{
 unsigned short int uiDateTimeDelta;
 unsigned short int uiAveragePressure;
 signed short int iAverageCountChannel1;
[…]
 signed short int iAverageCountChannelN;
 signed char cStdDeviationCountChannel1;
[…]
 signed char cStdDeviationCountChannelN;
}
 tMEC;
```

3 channels - Average + standard deviation data encoding				
Field	Format	Range	Resolution	Size (Byte)
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	SHORTINT	-64 to +4130	1	2
Channel 2 count	SHORTINT	-64 to +4130	1	2
Channel 3 count	SHORTINT	-64 to +4130	1	2
Standard deviation record				
Channel 1 count	BYTE	-128 to +127	1	1
Channel 2 count	BYTE	-128 to +127	1	1
Channel 3 count	BYTE	-128 to +127	1	1
				13

Averaged data and median – (AM)(MD)

```
struct
{
 unsigned short int uiDateTimeDelta;
 unsigned short int uiAveragePressure;
 signed short int iAverageCountChannel1;
[…]
 signed short int iAverageCountChannelN;
 unsigned short int uiMedianPressure;
 signed short int iMedianCountChannel1;
[…]
 signed short int iMedianCountChannelN;
}
 tMM;
```

3 channels - Average + median data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	SHORTINT	-64 to +4130	1	2
Channel 2 count	SHORTINT	-64 to +4130	1	2
Channel 3 count	SHORTINT	-64 to +4130	1	2
Median record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	SHORTINT	-64 to +4130	1	2
Channel 2 count	SHORTINT	-64 to +4130	1	2
Channel 3 count	SHORTINT	-64 to +4130	1	2
				18

Averaged data, standard deviation and median – (AM)(SD)(MD)

```
struct
{
 unsigned short int uiDateTimeDelta;
 unsigned short int uiAveragePressure;
 signed short int iAverageCountChannel1;
 [...]
 signed short int iAverageCountChannelN;
 signed char cStdDeviationCountChannel1;
 [...]
 signed char cStdDeviationCountChannelN;
 unsigned short int uiMedianPressure;
 signed short int iMedianCountChannel1;
 [...]
 signed short int iMedianCountChannelN;
}
 tMECM;
```

3 channels - Average + median data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	SHORTINT	-64 to +4130	1	2
Channel 2 count	SHORTINT	-64 to +4130	1	2
Channel 3 count	SHORTINT	-64 to +4130	1	2
Standard deviation record				
Channel 1 count	BYTE	-128 to +127	1	1
Channel 2 count	BYTE	-128 to +127	1	1
Channel 3 count	BYTE	-128 to +127	1	1
Median record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	SHORTINT	-64 to +4130	1	2
Channel 2 count	SHORTINT	-64 to +4130	1	2
Channel 3 count	SHORTINT	-64 to +4130	1	2
				21

Example:
[DESCENT]
(DW)
2018-11-08 16:13:01,3.7,4130,4130,4130
2018-11-08 16:13:07,4.2,4130,4130,4130

```
00000000   09 5b 44 45  53 43 45 4e   54 5d 28 44   57 29 8d 60   .[DESCENT] (DW) `
00000010   e4 5b 00 00  0d 04 22 10   22 10 22 10   06 00 12 04   ä[....".".".....
00000020   22 10 22 10  22 10 02 00   19 04 22 10   22 10 22 10   "."."....."."."."
00000030   02 00 1f 04  22 10 22 10   22 10 02 00   23 04 22 10   ....."."...#."."
00000040   22 10 22 10  02 00 2a 04   22 10 22 10   22 10 02 00   "."...*."."."...
```

Timestamp 1   = 1541693581 (0x5BE4608D) + 0 sec (0x0000) => 2018-11-08 16:13:01
Pressure 1   = 1037 (0x040D) => ((1037 / 10.0) − 100.0) = 3.7 dbar
Count 1   = 4130 (0x1022)
[...]
Timestamp 2   = Timestamp 1 + 6 sec (0x0006) => 2018-11-08 16:13:07
...

6.9. ECOv2 sensor

Data is encoded as follows:

- **Timestamping** of each record
- **Pressure** in cbar and +100 dbar offset (unsigned integer) – code = (value + 100.0) * 10.0
- **Channel count** (unsigned short int) – code = value
- **Channel count standard deviation** (signed int) – code = value

Data record can be composed of counts from 1 to 4 channels (depending on the sensor's configuration).

During the "descent" and "ascent" navigation phases, the first record of each processing area is timestamped in absolute value (reference date), then the recordings for the next records are timestamped in relative value by encoding the date in relation to the reference date (deviation in seconds).

During the "drift" phases, all records are timestamped in absolute value.

The available recording structures are as follows:

Raw data (park) – (RW) or (DW)
```
struct
{
 unsigned long int uliDateTime;
 unsigned short int uiPressure;
 unsigned short int uiCountChannel1;
[...]
 unsigned short int uiCountChannelN;
}
 tRPark;
```

3 channels - Raw data encoding (park)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	EPOCH	-	1 sec	4
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	USHORTINT	0 to +65000	1	2
Channel 2 count	USHORTINT	0 to +65000	1	2
Channel 3 count	USHORTINT	0 to +65000	1	2
				12

Raw data (navigation) – (RW) or (DW)

```
struct
{
 unsigned short int uiDateTimeDelta;
 unsigned short int uiPressure;
 unsigned short int uiCountChannel1;
[...]
 unsigned short int uiCountChannelN;
}
 tRNav;
```

3 channels - Raw data encoding (navigation)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	-	1 sec	2
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	USHORTINT	0 to +65000	1	2
Channel 2 count	USHORTINT	0 to +65000	1	2
Channel 3 count	USHORTINT	0 to +65000	1	2
				10

Averaged data – (AM)

```
struct
{
 unsigned short int uiDateTimeDelta;
 unsigned short int uiAveragePressure;
 unsigned short int uiAverageCountChannel1;
[...]
 unsigned short int uiAverageCountChannelN;
}
 tM;
```

3 channels - Average data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	USHORTINT	0 to +65000	1	2
Channel 2 count	USHORTINT	0 to +65000	1	2
Channel 3 count	USHORTINT	0 to +65000	1	2
				10

Averaged data and standard deviation – (AM)(SD)

```
struct
{
 unsigned short int uiDateTimeDelta;
 unsigned short int uiAveragePressure;
 unsigned short int uiAverageCountChannel1;
[...]
 unsigned short int uiAverageCountChannelN;
 signed short int iStdDeviationCountChannel1;
[...]
 signed short int iStdDeviationCountChannelN;
}
 tMEC;
```

Field	Format	Range	Resolution	Size (Byte)
3 channels - Average + standard deviation data encoding				
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	USHORTINT	0 to +65000	1	2
Channel 2 count	USHORTINT	0 to +65000	1	2
Channel 3 count	USHORTINT	0 to +65000	1	2
Standard deviation record				
Channel 1 count	SHORTINT	-32768 to +32767	1	2
Channel 2 count	SHORTINT	-32768 to +32767	1	2
Channel 3 count	SHORTINT	-32768 to +32767	1	2
				16

Averaged data and median – (AM)(MD)

```
struct
{
 unsigned short int uiDateTimeDelta;
 unsigned short int uiAveragePressure;
 unsigned short int uiAverageCountChannel1;
[...]
 unsigned short int uiAverageCountChannelN;
 unsigned short int uiMedianPressure;
 unsigned short int uiMedianCountChannel1;
[...]
 unsigned short int uiMedianCountChannelN;
}
 tMM;
```

3 channels - Average + median data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	USHORTINT	0 to +65000	1	2
Channel 2 count	USHORTINT	0 to +65000	1	2
Channel 3 count	USHORTINT	0 to +65000	1	2
Median record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	USHORTINT	0 to +65000	1	2
Channel 2 count	USHORTINT	0 to +65000	1	2
Channel 3 count	USHORTINT	0 to +65000	1	2
				18

Averaged data, standard deviation and median – (AM)(SD)(MD)

```
struct
{
 unsigned short int uiDateTimeDelta;
 unsigned short int uiAveragePressure;
 unsigned short int uiAverageCountChannel1;
 [...]
 unsigned short int uiAverageCountChannelN;
 signed short int iStdDeviationCountChannel1;
 [...]
 signed short int iStdDeviationCountChannelN;
 unsigned short int uiMedianPressure;
 unsigned short int uiMedianCountChannel1;
 [...]
 unsigned short int uiMedianCountChannelN;
}
 tMECM;
```

3 channels - Average + median data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	USHORTINT	0 to +65000	1	2
Channel 2 count	USHORTINT	0 to +65000	1	2
Channel 3 count	USHORTINT	0 to +65000	1	2
Standard deviation record				
Channel 1 count	SHORTINT	-32768 to +32767	1	2
Channel 2 count	SHORTINT	-32768 to +32767	1	2
Channel 3 count	SHORTINT	-32768 to +32767	1	2
Median record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Channel 1 count	USHORTINT	0 to +65000	1	2
Channel 2 count	USHORTINT	0 to +65000	1	2
Channel 3 count	USHORTINT	0 to +65000	1	2
				24

6.10.   CROVER sensor

Data is encoded as follows:

- **Timestamping** of each record
- **Pressure** in cbar and +100 dbar offset (unsigned integer) – code = (value + 100.0) * 10.0
- **Corrected signal raw count** (signed short int) – code = value
- **Corrected signal raw count standard deviation** (signed short int) – code = value

During the "descent" and "ascent" navigation phases, the first record of each processing area is timestamped in absolute value (reference date), then the recordings for the next records are timestamped in relative value by encoding the date in relation to the reference date (deviation in seconds).

During the "drift" phases, all records are timestamped in absolute value.

The available recording structures are as follows:

Raw data (park) – (RW) or (DW)
```
struct
{
  unsigned long int uliDateTime;
  unsigned short int uiPressure;
  signed short int iCorrectedSignalRawCount;
}
tRPark;
```

Raw data encoding (park)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	EPOCH	-	1 sec	4
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Corr Sig Raw	SHORTINT	-32768 to +32767	1	2
				8

Raw data (navigation) – (RW) or (DW)
```
struct
{
  unsigned short int uiDateTimeDelta;
  unsigned short int uiPressure;
  signed short int iCorrectedSignalRawCount;
}
tRNav;
```

Raw data encoding (navigation)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Corr Sig Raw	SHORTINT	-32768 to +32767	1	2
				6

Averaged data – (AM)

```
struct
{
 unsigned short int uiDateTimeDelta;
 unsigned short int uiAveragePressure;
 signed short int iAverageCorrectedSignalRawCount;
}
tM;
```

Average data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Corr Sig Raw	SHORTINT	-32768 to +32767	1	2
				6

Averaged data and standard deviation – (AM)(SD)

```
struct
{
 unsigned short int uiDateTimeDelta;
 unsigned short int uiAveragePressure;
 signed short int iAverageCorrectedSignalRawCount;
 signed short int iStdDeviationCorrectedSignalRawCount;
}
tMEC;
```

Average + standard deviation data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Corr Sig Raw	SHORTINT	-32768 to +32767	1	2
Standard deviation record				
Corr Sig Raw	SHORTINT	-32768 to +32767	1	2
				8

Averaged data and median – (AM)(MD)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  signed short int iAverageCorrectedSignalRawCount;
  unsigned short int uiMedianPressure;
  signed short int iMedianCorrectedSignalRawCount;
 }
tMM;
```

Average + standard deviation data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Corr Sig Raw	FLOAT	-32768 to +32767	1	2
Median record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Corr Sig Raw	SHORTINT	-32768 to +32767	1	2
				10

Averaged data, standard deviation and median – (AM)(SD)(MD)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  float fAverageBeamAttenuation;
  signed short int iStdDeviationCorrectedSignalRawCount;
  unsigned short int uiMedianPressure;
  signed short int iMedianCorrectedSignalRawCount;
 }
tMECM;
```

Average + standard deviation data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Corr Sig Raw	SHORTINT	-32768 to +32767	1	2
Standard deviation record				
Corr Sig Raw	SHORTINT	-32768 to +32767	1	2
Median record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Corr Sig Raw	SHORTINT	-32768 to +32767	1	2
				12

6.11.   SBEPH sensor

Data is encoded as follows:

- **Timestamping** of each record
- **Pressure** in cbar and +100 dbar offset (unsigned integer) – code = (value + 100.0) * 10.0
- **Voltage** in µV (signed long int) – code = (value * 1000000.0)
- **Voltage standard deviation** in µV (signed char) – code = (value * 1000000.0)

During the "descent" and "ascent" navigation phases, the first record of each processing area is timestamped in absolute value (reference date), then the recordings for the next records are timestamped in relative value by encoding the date in relation to the reference date (deviation in seconds).

During the "drift" phases, all records are timestamped in absolute value.

The available recording structures are as follows:

Raw data (park) – (RW) or (DW)
```
struct
{
 unsigned long int uliDateTime;
 unsigned short int uiPressure;
 signed long int liRefVoltage;
}
tRPark;
```

Raw data encoding (park)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	EPOCH	-	1 sec	4
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Voltage	LONGINT	-2500000 to +2500000 µV	1 µV	4
				10

Raw data (navigation) – (RW) or (DW)
```
struct
{
 unsigned short int uiDateTimeDelta;
 unsigned short int uiPressure;
 signed long int liRefVoltage;
}
tRNav;
```

Raw data encoding (navigation)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Voltage	LONGINT	-2500000 to +2500000 µV	1 µV	4
				8

Averaged data – (AM)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  signed long int liAverageRefVoltage;
 }
tM;
```

Average data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Voltage	LONGINT	-2500000 to +2500000 µV	1 µV	4
				8

Averaged data and standard deviation – (AM)(SD)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  signed long int liAverageRefVoltage;
  signed short int iStdDeviationRefVoltage;
 }
tMEC;
```

Average + standard deviation data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Voltage	LONGINT	-2500000 to +2500000 µV	1 µV	4
Standard deviation record				
Voltage	SHORTINT	-32768 to +32767 µV	1 µV	2
				10

Averaged data and median – (AM)(MD)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  signed long int liAverageRefVoltage;
  unsigned short int uiMedianPressure;
  signed long int liMedianRefVoltage;
 }
tMM;
```

Average + median data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Voltage	LONGINT	-2500000 to +2500000 µV	1 µV	4
Median record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Voltage	LONGINT	-2500000 to +2500000 µV	1 µV	4
				14

Averaged data, standard deviation and median – (AM)(SD)(MD)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  signed long int liAverageRefVoltage;
  signed short int iStdDeviationRefVoltage;
  unsigned short int uiMedianPressure;
  signed long int liMedianRefVoltage;
 }
tMECM;
```

Average + standard deviation + median data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Voltage	LONGINT	-2500000 to +2500000 µV	1 µV	4
Standard deviation record				
Voltage	SHORTINT	-32768 to +32767 µV	1 µV	2
Median record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Voltage	LONGINT	-2500000 to +2500000 µV	1 µV	4
				16

Example:
[DESCENT]
(AM)
2018-11-08 16:13:00,3.7,0.335851
2018-11-08 16:13:07,4.3,0.472219

00000000	0b	5b	44 45	53 43	45 4e	54 5d	28 41	4d 29	8c 60	.[DESCENT] (AM)Œ`
00000010	e4 5b	00 00	0d 04	eb 1f	05 00	07 00	13 04	9b 34	ä[....ë.......›4
00000020	07 00	04 00	1f 04	38 51	07 00	04 00	2a 04	26 5b	......8Q....*.&[
00000030	07 00	04 00	33 04	a8 5a	07 00	05 00	3c 04	d9 59	....3.¨Z....<.ÙY
00000040	07 00	05 00	46 04	33 56	07 00	04 00	50 04	6a 4a	....F.3V....P.jJ

Timestamp 1 = 1541693580 (0x5BE4608C) + 0 sec (0x0000) => 2018-11-08 16:13:00
Pressure 1 = 1037 (0x040D) => ((1037 / 10.0) − 100.0) = 3.7 dbar
Voltage = 335851 (0x00051FEB) => (335851 / 100000.0) = 0.335851 V
Timestamp 2 = Timestamp 1 + 7 sec (0x0007) => 2018-11-08 16:13:07

…

6.12. SUNA sensor

Data is encoded as follows:

- **Timestamping** of each record
- **Pressure** in cbar and +100 dbar offset (unsigned integer) – code = (value + 100.0) * 10.0
- **Temperature** in m°C and +5.0°C offset (unsigned integer) – code = (value + 5.0) * 1000.0
- **Salinity** in mpsu (unsigned integer) – code = value * 1000.0
- **Humidity** in % (unsigned char) – code = (value * 2.0)
- **Dark mean** (unsigned short int) – code = (value * 10.0)
- **Dark standard deviation** (signed short int) – code = (value * 100.0)
- **Nitrate concentration** in µM (float) – code = value
- **Absorbance fit residual RMS** (float) – code = value
- **Output spectrum** (unsigned short int) – code = value

Data record can be composed of output spectrum from 45 or 90 channels (depending on the sensor's configuration).

During the "descent" and "ascent" navigation phases, the first record of each processing area is timestamped in absolute value (reference date), then the recordings for the next records are timestamped in relative value by encoding the date in relation to the reference date (deviation in seconds).

During the "drift" phases, all records are timestamped in absolute value.

The available recording structures are as follows:

Raw data (park) – (RW) or (DW)
```
struct
{
unsigned long int uliDateTime;
struct
{
 struct
 {
  unsigned short int uiPressure;
  unsigned short int uiTemperature;
  unsigned short int uiSalinity;
 }
 tCTD;
 unsigned short int uiInternalTemperature;
 unsigned short int uiSpectrometerTemperature;
 unsigned char ucInternalRelativeHumidity;
 struct
 {
  unsigned short int uiMean;
  signed short int iStandardDeviation;
 }
 tDarkSpectrum;
 struct
```

```
{
 float fNitrate;
 }
 tSensor;
 float fAbsorbanceFitResiduals;
 struct
 {
 unsigned short int tuiSpectrum[ N ];
 }
 tOutput;
 }
 tAPFData;
 }
 tRPark;
```

45 outputs spectrum - Raw data encoding (park)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	EPOCH	-	1 sec	4
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Salinity	SHORTINT	0.0 to +50.0 psu	0.001 psu	2
Temperature int.	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Temperature spec.	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Relative humidity	BYTE	0.0 to +100% RH	0.5% RH	1
Dark M	SHORTINT	0.0 to +6553.5	0.1	2
Dark SD	SHORTINT	-327.68 to +327.67	0.01	2
Nitrate	FLOAT	IEEE float	IEEE float	4
Absorbance	FLOAT	IEEE float	IEEE float	4
Output 1	SHORTINT	0 to +65535	1	2
...	-	-	-	-
Output 45	SHORTINT	0 to +65535	1	2
				117

Raw data (navigation) – (RW) or (DW)

```
struct
{
unsigned short int uiDateTimeDelta;
struct
{
 struct
 {
  unsigned short int uiPressure;
  unsigned short int uiTemperature;
  unsigned short int uiSalinity;
 }
 tCTD;
 unsigned short int uiInternalTemperature;
 unsigned short int uiSpectrometerTemperature;
 unsigned char ucInternalRelativeHumidity;
 struct
 {
  unsigned short int uiMean;
  signed short int iStandardDeviation;
 }
 tDarkSpectrum;
 struct
 {
  float fNitrate;
 }
 tSensor;
 float fAbsorbanceFitResiduals;
 struct
 {
  unsigned short int tuiSpectrum[ N ];
 }
 tOutput;
}
tAPFData;
}
tRNav;
```

45 outputs spectrum - Raw data encoding (navigation)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535	1 sec	2
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Salinity	SHORTINT	0.0 to +50.0 psu	0.001 psu	2
Temperature int.	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Temperature spec.	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Relative humidity	BYTE	0.0 to +100% RH	0.5% RH	1
Dark M	SHORTINT	0.0 to +6553.5	0.1	2

Dark SD	SHORTINT	-327.68 to +327.67	0.01	2
Nitrate	FLOAT	IEEE float	IEEE float	4
Absorbance	FLOAT	IEEE float	IEEE float	4
Output 1	SHORTINT	0 to +65535	1	2
...	-	-	-	-
Output 45	SHORTINT	0 to +65535	1	2
				115

Example:
[DESCENT]
(DW)
2018-11-21 10:38:51,1.5,17.486,[...],8.0,[...]
2018-11-21 10:39:20,9.2,[...]

```
00000000   0c 5b 44 45  53 43 45 4e  54 5d 28 44  57 29 bb 35   .[DESCENT] (DW)»5
00000010   f5 5b 00 00  f7 03 d6 57  d7 8b ba 68  42 68 10 06   õ[..÷.ÖW×‹°hBh..
00000020   1d 84 03 1f  85 5c c2 94  87 85 3c c0  9c a7 a7 ea   .„…..\Â"‡…<Àœ§§ê
00000030   b3 8c c0 fd  cc 95 d8 2a  e2 00 e9 2c  ec 72 eb 7c   ³ŒÀýÌ•Ø*â.é,ìrë|
00000040   e7 87 e0 9b  d7 04 ce 98  c4 f1 bb 74  b4 a2 ae 11   ç‡à›×.Î˜Äñ»t´¢®.
00000050   aa 08 a7 62  a5 f4 a4 b6  a5 54 a7 04  aa 91 ad 45   ª.§b¥ô¤¶¥T§.ª'E
00000060   b2 a9 b7 d6  bd 95 c4 cc  cb 40 d3 74  da d8 e0 40   ²©·Ö½•ÄÌË@ÓtÚØà@
00000070   e6 bd e9 00  eb e8 e9 53  e6 4c e0 b1  d8 39 cf 00   æ½é.ëèéSæLà±Ø9Ï.
00000080   00 00 00 00  00 1d 00 44  04 a4 57 d4  8b 00 69 7e   .......D.¤WÔ‹.i~
00000090   68 10 06 1d  20 03 3d 0a  5c c2 85 b1  85 3c 8c 9c   h... .=.\Â…±…<Œœ
000000a0   83 a7 a7 b3  4d c0 bc cc  42 d8 e0 e1  be e8 e1 eb   ƒ§§³MÀ¼ÌBØàá¾èáë
000000b0   22 eb 25 e7  38 e0 5e d7  c6 cd 56 c4  ca bb 44 b4   "ë%ç8à^×ÆÍVÄÊ»D´
000000c0   68 ae f7 a9  e2 a6 4a a5  b9 a4 82 a5  20 a7 d4 a9   h®÷©â¦J¥¹¤‚¥ §Ô©
000000d0   69 ad 04 b2  67 b7 9c bd  6e c4 86 cb  0a d3 4a da   i.²g·œ½nÄ†Ë.ÓJÚ
000000e0   8a e0 ec e5  74 e9 b4 ea  a1 e9 21 e6  30 e0 88 d8   Šàìåté´ê¡é!æ0à^Ø
000000f0   21 cf 00 00  00 00 00 00  1e 00 7e 04  79 57 d1 8b   !Ï........~.yWÑ‹
```

Timestamp 1   = 1542796731 (0x5BE435BB) + 0 sec (0x0000) => 2018-11-21 10:38:51
Pressure 1   = 1015 (0x03F7) => ((1015 / 10.0) − 100.0) = 1.5 dbar
Temperature 1 = 22486 (0x57D6) => ((22486 / 1000.0) − 5.0) = 17.486°C
[...]
Humidity 1   = 16 (0x10) => (16 / 2.0) = 8.0 % RH
Timestamp 2   = Timestamp 1 + 29 sec (0x001D) => 2018-11-21 10:39:20
…

6.13. UVP6 sensor (LPM/LPMv2)

Data is encoded as follows:

- **Timestamping** of each record
- **Number of images** in a record (unsigned char) – code = value
- **Pressure** in cbar and +100 dbar offset (unsigned integer) – code = (value + 100.0) * 10.0
- **Temperature int.** in m°C and +5.0°C offset (unsigned integer) – code = (value + 5.0) * 1000.0
- **Number of particles per size class** (float) – code = value
- **Mean grey level per size class** (unsigned char) – code = value

During the "descent" and "ascent" navigation phases, the first record of each processing area is timestamped in absolute value (reference date), then the recordings for the next records are timestamped in relative value by encoding the date in relation to the reference date (deviation in seconds).

During the "drift" phases, all records are timestamped in absolute value.

Raw data (park) – (RW) or (DW)
```
struct
 {
  unsigned long int uliDateTime;
  unsigned char ucImageNumber;
  unsigned short int uiPressure;
  unsigned short int uiInternalTemperature;
  float tfObjectCount[ 18 ];
  unsigned char tucGreyLevel[ 18 ];
 }
 tRPark;
```

Raw data encoding (park)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	EPOCH	-	1 sec	4
Raw record				
Image number	BYTE	1 to +255	1	1
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature int.	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Particles 1 count	FLOAT	IEEE float	IEEE float	4
...	-	-	-	16*4
Particles 18 count	FLOAT	IEEE float	IEEE float	4
Grey level 1	BYTE	0 to 255	1	1
...	-	-	-	16*1
Grey level 18	BYTE	0 to 255	1	1
				99

Raw data (navigation) – (RW) or (DW)
```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned char ucImageNumber;...................................................................LPMv2 only
  unsigned short int uiPressure;
  unsigned short int uiInternalTemperature;
  float tfObjectCount[ 18 ];
  unsigned char tucGreyLevel[ 18 ];
 }
 tRNav;
```

Raw data encoding (navigation)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535	1 sec	2
Raw record				
Image number	BYTE	1 to +255	1	1
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature int.	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Particles 1 count	FLOAT	IEEE float	IEEE float	4
...	-	-	-	16*4
Particles 18 count	FLOAT	IEEE float	IEEE float	4
Grey level 1	BYTE	0 to 255	1	1
...	-	-	-	16*1
Grey level 18	BYTE	0 to 255	1	1
				96/97

Averaged data – (AM)
```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiImageNumber;
  unsigned short int uiAveragePressure;
  unsigned short int uiInternalTemperature;
  float tfObjectCount[ 18 ];
  unsigned char tucGreyLevel[ 18 ];
 }
 tM;
```

Average data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535	1 sec	2
Average record				
Image number	SHORTINT	1 to +65535	1	2
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature int.	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Particles 1 count	FLOAT	IEEE float	IEEE float	4
...	-	-	-	16*4
Particles 18 count	FLOAT	IEEE float	IEEE float	4
Grey level 1	BYTE	0 to 255	1	1
...	-	-	-	16*1
Grey level 18	BYTE	0 to 255	1	1
				98

Example:
[DESCENT]
(DW)
2019-09-23 15:29:34,0,0.00,24.31,27682.0000,2576.0000,0.0000,510.0000,[...],2,2,0,2,2,2,2,0,[...]

```
00000000   0e 5b 44 45  53 43 45 4e  54 5d 28 44  57 29 de e4   .[DESCENT](DW)Þä
00000010   88 5d 00 00  e8 03 7e 72  00 44 d8 46  00 00 21 45   ^]..è.~r.DØF..!E
00000020   00 00 00 00  00 00 ff 43  00 00 e0 41  00 00 c0 40   ......ÿC..àA..À@
00000030   00 00 80 3f  00 00 00 00  00 00 00 00  00 00 00 00   ..€?............
00000040   00 00 00 00  00 00 00 00  00 00 00 00  00 00 00 00   ................
00000050   00 00 00 00  00 00 00 00  00 00 00 00  00 00 00 00   ................
00000060   02 02 00 02  02 02 02 00  00 00 00 00  00 00 00 00   ................
```

Timestamp 1   = 1569252574 (0x5D88E4DE) + 0 sec (0x0000) => 2019-09-23 15:29:34
Pressure 1   = 1015 (0x03E8) => ((1000 / 10.0) – 100.0) = 0.0 dbar
Temperature 1 = 29310 (0x727E) => ((29310 / 1000.0) – 5.0) = 24.310°C
Particle 1/18 1 = 27682.0 (0x46D84400)
[...]
Grey level 1   = 2 (0x02)

6.14. UVP6 sensor (TAXOv2)

Data is encoded as follows:

- **Timestamping** of each record
- **Number of images** in a record (unsigned char) – code = value
- **Pressure** in cbar and +100 dbar offset (unsigned integer) – code = (value + 100.0) * 10.0
- **Number of object** in the record (unsigned char) – code = value (1 to 25 max.)
- **Object index** (unsigned char) – code = value (1 to 40)
- **Mean size per an object** (float) – code = value
- **Mean grey level per an object** (unsigned char) – code = value

During the "descent" and "ascent" navigation phases, the first record of each processing area is timestamped in absolute value (reference date), then the recordings for the next records are timestamped in relative value by encoding the date in relation to the reference date (deviation in seconds).

During the "drift" phases, all records are timestamped in absolute value.

This data type has the particularity to use a variable size record. Each record could have different size. The size of the packet is determinate by the field "number of object".

Raw data (park) – (RW) or (DW)
```
struct
 {
  unsigned long int uliDateTime;
  unsigned char ucImageNumber;
  unsigned short int uiPressure;
  unsigned char ucObjectNumber;
  struct
   {
    unsigned char ucObjectIndex;
    float fSize;
    unsigned char ucGreyLevel;
   }
  ttObject[ 1 to 25 ];
 }
tRPark;
```

Raw data encoding (park)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	EPOCH	-	1 sec	4
Raw record				
Image number	BYTE	1 to +255	1	1
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Object number	BYTE	1 to 25	1	1
Object index 1	BYTE	0 to 39	1	1
Object size 1	FLOAT	IEEE float	IEEE float	4
Object grey level 1	BYTE	0 to +255	1	1

...	-	-	-	-
Object index N	BYTE	0 to 39	1	1
Object size N	FLOAT	IEEE float	IEEE float	4
Object grey level N	BYTE	0 to +255	1	1
				8+(N*6)

Raw data (navigation) – (RW) or (DW)
```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned char ucImageNumber;
  unsigned short int uiPressure;
  unsigned char ucObjectNumber;
  struct
   {
    unsigned char ucObjectIndex;
    float fSize;
    unsigned char ucGreyLevel;
   }
  ttObject[ 1 to 25 ];
 }
tRNav;
```

Raw data encoding (navigation)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535	1 sec	2
Raw record				
Image number	BYTE	1 to +255	1	1
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Object number	BYTE	1 to 25	1	1
Object index 1	BYTE	0 to 39	1	1
Object size 1	FLOAT	IEEE float	IEEE float	4
Object grey level 1	BYTE	0 to +255	1	1
...	-	-	-	-
Object index N	BYTE	0 to 39	1	1
Object size N	FLOAT	IEEE float	IEEE float	4
Object grey level N	BYTE	0 to +255	1	1
				6+(N*6)

Average data – (AM)
```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAverageNumber;
  unsigned short int uiPressure;
  unsigned char ucObjectNumber;
  struct
   {
```

```
    unsigned char ucObjectIndex;
    float fSize;
    unsigned char ucGreyLevel;
  }
 ttObject[ 1 to 25 ];
 }
tM;
```

Average data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535	1 sec	2
Average record				
Image number	SHORTINT	1 to +65535	1	2
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Object number	BYTE	1 to 25	1	1
Object index 1	BYTE	0 to 39	1	1
Object size 1	FLOAT	IEEE float	IEEE float	4
Object grey level 1	BYTE	0 to +255	1	1
...	-	-	-	-
Object index N	BYTE	0 to 39	1	1
Object size N	FLOAT	IEEE float	IEEE float	4
Object grey level N	BYTE	0 to +255	1	1
				7+(N*6)

6.15.   UVP6 sensor (BLACK/BLACKv2)

Data is encoded as follows:

- **Timestamping** of each record
- **Number of images** in a record (unsigned char) – code = value
- **Pressure** in cbar and +100 dbar offset (unsigned integer) – code = (value + 100.0) * 10.0
- **Internal temperature** in m°C and +5.0°C offset (unsigned integer) – code = (value + 5.0) * 1000.0
- **Number of particles per size class** (unsigned integer) – code = value

All records are timestamped in absolute value.

Raw data – (RW)
```
struct
 {
  unsigned long int uliDateTime;
  unsigned char ucImageNumber;.................................................................BLACKv2 only
  unsigned short int uiPressure;
  unsigned short int uiInternalTemperature;
  unsigned short int tuiObjectCount[ 5 ];
 }
 tR;
```

Raw data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	EPOCH	-	1 sec	4
Raw record				
Image number	BYTE	1 to +255	1	1
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Temperature int.	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Particles 1 count	SHORTINT	0 to +65535	1	2
...	-	-	-	3*2
Particles 5 count	SHORTINT	0 to +65535	1	2
				18

Example:
[DESCENT]
(RW)
2019-04-30 14:56:26,3.3,1,31.94,8504,1001,0,511,88
2019-04-30 14:56:57,10.9,1,31.94,12702,1226,0,591,128

```
00000000  11 5b 44 45   53 43 45 4e   54 5d 28 52   57 29 1a 62   .[DESCENT] (RW) .b
00000010  c8 5c 09 04   01 4c 90 38   21 e9 03 00   00 ff 01 58   È\...L 8!é...ÿ.X
00000020  00 39 62 c8   5c 55 04 01   4c 90 9e 31   ca 04 00 00   .9bÈ\U..L ž1Ê...
00000030  4f 02 80 00   69 62 c8 5c   b5 04 01 88   90 11 3f 0d   O.€.ibÈ\µ..ˆ .?.
00000040  06 00 00 5e   02 67 00 5b   50 41 52 4b   5d 78 62 c8   ...^.g.[PARK]xbÈ
00000050  5c cb 04 01   88 90 c8 2f   c1 04 00 00   2a 02 73 00   \Ë..ˆ È/Á...*.s.
```

Timestamp 1	= 1556636188 (0x5CC8621A) => 2019-04-30 14:56:26
Pressure 1	= 1033 (0x0409) => ((1033 / 10.0) − 100.0) = 3.3 dbar
Temperature 1	= 36940 (0x904C) => ((36940 / 1000.0) − 5.0) = 31.94°C
Object count class_1 1	= 8504 (0x2138)
[...]	
Timestamp 2	= 1556636217 (0x5CC86239) => 2019-04-30 14:56:57
Pressure 2	= 1109 (0x0455) => ((1109 / 10.0) − 100.0) = 10.9 dbar
...	

6.16. EXTTRIG sensor

Data is encoded as follows:

- **Timestamping** of each record
- **Pressure** in cbar and +100 dbar offset (unsigned integer) – code = (value + 100.0) * 10.0

All records are timestamped in absolute value. So, there are no processing type identification strings inserted in the data file.

Raw data – (RW)

```
struct
 {
  unsigned long int uliDateTime;
  unsigned short int uiPressure;
 }
 tR;
```

Raw data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	EPOCH	-	1 sec	4
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
				6

Example:
[DESCENT]
(RW)
2020-01-20 14:08:53,0.0
2020-01-20 14:08:55,0.0

Timestamp 1	= 1579529333 (0x5E25B475) => 2020-01-20 14:08:53
Pressure 1	= 1000 (0x03E8) => ((1000 / 10.0) – 100.0) = 0.0 dbar
Timestamp 2	= 1579529335 (0x5E25B477) => 2020-01-20 14:08:55
Pressure 2	= 1000 (0x03E8) => ((1000 / 10.0) – 100.0) = 0.0 dbar
...	

6.17. RAMSES sensor

Data is encoded as follows:

- **Timestamping** of each record
- **Pressure** in cbar and +100 dbar offset (unsigned integer) – code = (value + 100.0) * 10.0
- **Integration time** (unsigned integer) – code = value
- **Depth** in cbar and +100 dbar offset (unsigned integer) – code = (value + 100.0) * 20.0
- **Inclination** in cdegree (unsigned integer) – code = (value + 100.0) * 10.0
- **Dark average** (unsigned integer) – code = value
- **Number of spectrum channels** (unsigned char) – code = value
- **Spectrum channels count** (unsigned integer) – code = value (spectrum size is not constant)

During the "descent" and "ascent" navigation phases, the first record of each processing area is timestamped in absolute value (reference date), then the recordings for the next records are timestamped in relative value by encoding the date in relation to the reference date (deviation in seconds).

During the "drift" phases, all records are timestamped in absolute value.

Raw data (park) – (RW) or (DW)
```
struct
 {
  unsigned long int uliDateTime;
  unsigned short int uiPressure;
  unsigned short int uiIntegrationTime;
  unsigned short int uiPrePressure;
  unsigned short int uiPostPressure;
  unsigned short int uiPreInclination;
  unsigned short int uiPostInclination;
  unsigned short int uiDark;
  unsigned char ucSpectrumSize;
  unsigned short int tuiSpectrum[ 245 max ];
 }
 tRPark;
```

Raw data encoding (park)				
Field	Format	Range	Resolution	Size (Byte)
Timestamp	EPOCH	-	1 sec	4
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Integration time	SHORTINT	0 to +65535	1	2
Pre-Pressure	SHORTINT	-100 to +2500 dbar	0.05 dbar	2
Post-Pressure	SHORTINT	-100 to +2500 dbar	0.05 dbar	2
Pre-Inclination	SHORTINT	0 to +360°	0.01°	2
Post-Inclination	SHORTINT	0 to +360°	0.01°	2
Dark average	SHORTINT	0 to +65535	1	2
Channel number N	BYTE	0 to +245	1	1

Channel 1 count	SHORTINT	0 to +65535	1	2
...	-	-	-	(N-2)*2
Channel N count	SHORTINT	0 to +65535	1	2
				19+2N

Raw data (navigation) – (RW) or (DW)
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiPressure;
  unsigned short int uiIntegrationTime;
  unsigned short int uiPrePressure;
  unsigned short int uiPostPressure;
  unsigned short int uiPreInclination;
  unsigned short int uiPostInclination;
  unsigned short int uiDark;
  unsigned char ucSpectrumSize;
  unsigned short int tuiSpectrum[245 max];
 }
 tRNav;

Raw data encoding (navigation)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535	1 sec	2
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Integration time	SHORTINT	0 to +65535	1	2
Pre-Pressure	SHORTINT	-100 to +2500 dbar	0.05 dbar	2
Post-Pressure	SHORTINT	-100 to +2500 dbar	0.05 dbar	2
Pre-Inclination	SHORTINT	0 to +360°	0.01°	2
Post-Inclination	SHORTINT	0 to +360°	0.01°	2
Dark average	SHORTINT	0 to +65535	1	2
Channel number N	BYTE	0 to +245	1	1
Channel 1 count	SHORTINT	0 to +65535	1	2
...	-	-	-	(N-2)*2
Channel N count	SHORTINT	0 to +65535	1	2
				17+2N

Example:
[DESCENT]
(DW)
2020-03-30 12:26:36,0.60,4096,0.95,0.95,271.27,271.28,1785,50,1758,1755,1762,[...],4865
2020-03-30 12:26:38,1.50,4096,0.95,0.95,271.27,271.28,1785,50,1758,1755,1762,[...],4865

```
00000000   17 5b 44 45  53 43 45 4e  54 5d 28 44  57 29 7c e5   .[DESCENT] (DW)|å
00000010   81 5e 00 00  ee 03 00 10  e3 07 e3 07  f7 69 f8 69   ^..î...ã.ã.÷iøi
00000020   f9 06 32 de  06 db 06 e2  06 e7 06 e2  06 e6 06 ec   ù.2Þ.Û.â.ç.â.æ.ì
00000030   06 ee 06 f0  06 fb 06 fb  06 06 07 16  07 44 07 d3   .î.ð.û.û.....D.Ó
00000040   07 c2 08 f4  09 35 0b e5  0c 67 10 3d  13 e4 14 7e   .Â.ô.5.å.g.=.ä.~
00000050   14 44 13 16  12 8f 11 3f  11 57 11 4d  12 33 14 d8   .D... .?.W.M.3.Ø
00000060   16 41 18 b7  18 f3 18 89  19 86 1b f6  19 f5 17 30   .A.·.ó.‰.†.ö.õ.0
00000070   17 cc 16 d7  16 12 16 ac  15 6d 15 e6  15 c8 19 4c   .Ì.×...¬.m.æ.È.L
00000080   1d 89 18 07  14 01 13 02  00 f7 03 00  10 e3 07 e3   .‰.......÷...ã.ã
```

Timestamp 1   = 1585571196 (0x5E81E57C) => 2020-03-30 12:26:36
Pressure 1   = 1006 (0x03EE) => ((1006 / 10.0) – 100.0) = 0.6 dbar
Pre-Inclination 1   = 27128 (0x69F7) => (27127 * 100.0) = 271.28°
Channel number 1   = 50 (0x32)
[...]
Timestamp 2   = Timestamp 1 + 2 sec (0x0002) => 2020-03-30 12:26:38

6.18. OPUS sensor (LIGHT)

Data is encoded as follows:

- **Timestamping** of each record
- **Pressure** in cbar and +100 dbar offset (unsigned integer) – code = (value + 100.0) * 10.0
- **Spectrum type** (char) – code = '2' for calibrated spectrum and '4' for raw light spectrum
- **Averaging** (unsigned char) – code = value * 10
- **Flash count** (unsigned char) – code = value * 10
- **Internal temperature** in m°C and +5.0°C offset (unsigned integer) – code = (value + 5.0) * 1000.0
- **Number of spectrum channels** (unsigned char) – code = value
- **Spectrum channels count** (unsigned integer) – code = value (spectrum size is not constant)

During the "descent" and "ascent" navigation phases, the first record of each processing area is timestamped in absolute value (reference date), then the recordings for the next records are timestamped in relative value by encoding the date in relation to the reference date (deviation in seconds).

During the "drift" phases, all records are timestamped in absolute value.

Raw data (park) – (RW) or (DW)
```
struct
 {
  unsigned long int uliDateTime;
  unsigned short int uiPressure;
  char cSpectrumType;
  unsigned char ucAveraging;
  unsigned char ucFlashCount;
  unsigned short int uiTemperature;
  unsigned char uiSpectrumSizeN;
  unsigned short int tuiSpectrumN[ 255 max ];
  unsigned char uiSpectrumSizeM;
  unsigned short int tuiSpectrumM[ 255 max ];
 }
 tRPark;
```

Raw data encoding (park)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	EPOCH	-	1 sec	4
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Spectrum type	BYTE	'2': calibrated / '4': raw	1	1
Averaging	BYTE	0 to 25.0	0.1	1
Flash count	BYTE	0 to 25.0	0.1	1
Temperature int.	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Channel number N	BYTE	0 to +255	1	1
Channel F1 count	SHORTINT	0 to +65535	1	2

...	-	-	-	(N-2)*2
Channel FN count	SHORTINT	0 to +65535	1	2
Channel number M	BYTE	0 to +255	1	1
Channel B1 count	SHORTINT	0 to +65535	1	2
...	-	-	-	(M-2)*2
Channel BM count	SHORTINT	0 to +65535	1	2
				13+2N+2M

Raw data (navigation) – (RW) or (DW)/Averaged data – (AM)
```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiPressure;
  char cSpectrumType;
  unsigned char ucAveraging;
  unsigned char ucFlashCount;
  unsigned short int uiTemperature;
  unsigned char uiSpectrumSizeN;
  unsigned short int tuiSpectrumN[ 255 max ];
  unsigned char uiSpectrumSizeM;
  unsigned short int tuiSpectrumM[ 255 max ];
 }
 tRNav/tM;
```

Raw data encoding (navigation)/ Average data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535	1 sec	2
Raw record/Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Spectrum type	BYTE	'2': calibrated / '4': raw	1	1
Averaging	BYTE	0 to 25.0	0.1	1
Flash count	BYTE	0 to 25.0	0.1	1
Temperature int.	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Channel number N	BYTE	0 to +255	1	1
Channel F1 count	SHORTINT	0 to +65535	1	2
...	-	-	-	(N-2)*2
Channel FN count	SHORTINT	0 to +65535	1	2
Channel number M	BYTE	0 to +255	1	1
Channel B1 count	SHORTINT	0 to +65535	1	2
...	-	-	-	(M-2)*2
Channel BM count	SHORTINT	0 to +65535	1	2
				11+2N+2M

Example:
[ASCENT]
(RW)
2020-03-30 12:26:36,1001.0,4,3.0,1.0,25.750,31,16515,[…],19,25358,[…]

```
00000000   18 5b 41 53  43 45 4e 54   5d 28 52 57   29 7c e5 81   .[ASCENT] (RW)|å
00000010   5e 00 00 02  2b 34 1e 0a   1e 78 1f 83   40 7a 3e ca   ^...+4...x.ƒ@z>Ê
00000020   3b 87 39 25  38 41 37 14   37 89 37 94   37 23 38 01   ;‡9%8A7.7%7"7#8.
00000030   3a 6a 3e ad  47 4d 57 77   72 3d 9a 80   b5 28 ac 2e   :j>-GMWwr=š€µ(¬.
00000040   92 6c 7e 43  6f fe 67 25   69 f2 68 8f   65 af 61 e5   'l~Coþg%iòh e¯aå
00000050   5c 8a 58 2d  56 ca 56 72   5d 13 0e 63   07 3e bf 2f   \ŠX-VÊVr\..c.>¿/
00000060   49 38 72 2e  41 20 09 1e   9a 21 7e 2a   f7 25 6d 1e   I8r.A ..š!~*÷%m.
00000070   33 17 b4 12  4c 11 31 11   7f 11 36 12   a8 12 d5 13   3.´.L.1.[.6.¨.Õ.
00000080   28 52 57 29  ef 07 5c 49   00 00 74 09   34 1e 0a 6b   (RW)ï.\I..t.4..k
```

Timestamp 1	= 1585571196 (0x5E81E57C) => 2020-03-30 12:26:36
Pressure 1	= 11010 (0x2B02) => ((11010 / 10.0) – 100.0) = 1001.0 dbar
Spectrum type 1	= "4" (0x34)
Averaging 1	= 30 (0x1E) => (30 / 10.0) = 3.0
Flash count 1	= 10 (0x0A) => (10 / 10.0) = 1.0
Temperature 1	= 30730 (0x781E) => ((30750 / 1000.0) – 5.0) = 25.750°C
Spectrum size N 1	= 31 (0x1F)
Channel F1 1	= 16515 (0x4083)
[…]	
Spectrum size M 1	= 19 (0x13)
Channel B1 1	= 25358 (0x630E)
[…]	

6.19.   OPUS sensor (BLACK)

Data is encoded as follows:

-   **Timestamping** of each record
-   **Pressure** in cbar and +100 dbar offset (unsigned integer) – code = (value + 100.0) * 10.0
-   **Averaging** (unsigned char) – code = value * 10
-   **Flash count** (unsigned char) – code = value * 10
-   **Internal temperature** in m°C and +5.0°C offset (unsigned integer) – code = (value + 5.0) * 1000.0
-   **Dark mean** (float) – code = value
-   **Dark standard deviation** (float) – code = value

All records are timestamped in absolute value.

Raw data – (RW)
```
struct
 {
  unsigned long int uliDateTime;
  unsigned short int uiPressure;
  unsigned char ucAveraging;
  unsigned char ucFlashCount;
  unsigned short int uiTemperature;
  float fDarkMean;
  float fDarkStdDev;
 }
tR;
```

Raw data encoding (park)				
Field	Format	Range	Resolution	Size (Byte)
Timestamp	EPOCH	-	1 sec	4
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Averaging	BYTE	0 to 25.0	0.1	1
Flash count	BYTE	0 to 25.0	0.1	1
Temperature int.	SHORTINT	-5.0 to +40.0°C	0.001°C	2
Dark mean	FLOAT	IEEE float	IEEE float	4
Dark standard dev	FLOAT	IEEE float	IEEE float	4
				18

Example:
[ASCENT]
(RW)
2020-03-30 12:26:36,1001.0,3.0,1.0,25.687,23217.0,8959.0

```
00000000   19 5b 41 53   43 45 4e 54   5d 28 52 57   29 7c e5 81   .[ASCENT] (RW) |å
00000010   5e 02 2b 1e   0a df 77 16   62 b5 46 19   fc 0b 46 08   ^.+..ßw.bµF.ü.F.
00000020   08 5c 49 02   2b 1e 0a 86   78 c8 3f b6   46 17 68 0c   .\I.+..†xÈ?¶F.h.
00000030   46 28 52 57   29 28 08 5c   49 6a 09 1e   0a 56 79 f8   F(RW)(.\Ij...Vyø
```

Timestamp 1	= 1585571196 (0x5E81E57C) => 2020-03-30 12:26:36
Pressure 1	= 11010 (0x2B02) => ((11010 / 10.0) – 100.0) = 1001.0 dbar
Averaging 1	= 30 (0x1E) => (30 / 10.0) = 3.0
Flash count 1	= 10 (0x0A) => (10 / 10.0) = 1.0
Temperature 1	= 30687 (0x77DF) => ((30687 / 1000.0) – 5.0) = 25.687°C
Dark mean 1	= 23217.0 (0x46B56216)
Dark std deviation 1	= 8959.0 (0x460BFC19)
[…]	

6.20. MPE sensor

Data is encoded as follows:

- **Timestamping** of each record
- **Pressure** in cbar and +100 dbar offset (unsigned integer) – code = (value + 100.0) * 10.0
- **Voltage** in xV (float) – code = value
- **Temperature** in m°C and +5.0°C offset (unsigned integer) – code = (value + 5.0) * 1000.0

During the "descent" and "ascent" navigation phases, the first record of each processing area is timestamped in absolute value (reference date), then the recordings for the next records are timestamped in relative value by encoding the date in relation to the reference date (deviation in seconds).

During the "drift" phases, all records are timestamped in absolute value.

The available recording structures are as follows:

Raw data (park) – (RW) or (DW)
```
struct
 {
  unsigned long int uliDateTime;
  unsigned short int uiPressure;
  float fVoltage;
  unsigned short int uiTemperature;
 }
 tRPark;
```

Raw data encoding (park)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	EPOCH	-	1 sec	4
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Voltage	FLOAT	-5.0e-03 to +1.6e+05 xV	IEEE float	4
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
				12

Raw data (navigation) – (RW) or (DW)
```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiPressure;
  float fVoltage;
  unsigned short int uiTemperature;
 }
 tRNav;
```

Raw data encoding (navigation)				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Raw record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Voltage	FLOAT	-5.0e-03 to +1.6e+05 xV	IEEE float	4
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
				10

Averaged data – (AM)

```
struct
 {
  unsigned short int uiDateTimeDelta;
  unsigned short int uiAveragePressure;
  float fAverageVoltage;
  unsigned short int uiAverageTemperature;
 }
 tM;
```

Average data encoding				
Field	**Format**	**Range**	**Resolution**	**Size (Byte)**
Timestamp	SHORTINT	0 to +65535 sec	1 sec	2
Average record				
Pressure	SHORTINT	-100 to +2500 dbar	0.1 dbar	2
Voltage	FLOAT	-5.0e-03 to +1.6e+05 xV	IEEE float	4
Temperature	SHORTINT	-5.0 to +40.0°C	0.001°C	2
				10

Example:
[DESCENT]
(DW)
2021-01-28 15:22:56,0.00,4.567e-04,15.3


```
00000000   1a 5b 44 45  53 43 45 4e  54 5d 28 44  57 29 d0 d6   .[DESCENT](DW)ÐÖ
00000010   12 60 00 00  e8 03 3d 71  ef 39 4c 4f  28 44 57 29   .`..è.=qï9LO(DW)
00000020   de d6 12 60  00 00 ec 03  3d 71 ef 39  4c 4f 28 44   ÞÖ.`..ì.=qï9LO(D
```

Timestamp 1 = 1611847376 (0x6012D6D0) => 2021-01-28 15:22:56
Pressure 1 = 1000 (0x03E8) => ((1000 / 10.0) − 100.0) = 0.0 dbar
Voltage 1 = 4.567e-04 (0x39EF713D)
Temperature 1 = 20300 (0x4F4C) => ((20300 / 1000.0) − 5.0) = 15.3°C